

1. Problems 5.2a,b. (*Pressure gradient*) (For 5.2a, scan, photocopy, or trace the map.) For 5.2b, you'll have to work out or look up the distance across Ireland in the relevant direction.) [5+5=10 pts.]

Solution:

- a. The gradient vector is perpendicular to the contours of constant pressure, points in the direction of increasing pressure, and has a length inversely proportional to the distance between neighboring contours.
- b. The pressure changes by $1030 - 1025 = 5$ millibars in what looks to me on a map of Ireland to be about 400 km, so the magnitude of the gradient is about 0.013 millibars/km. It is larger over Iceland since the pressure changes by the same amount in a shorter distance of about 200 km. Hence the gradient is about twice as large over Iceland as over Ireland.
2. Consider the function $f(x, y, z) = ax^2 + by^2 + cz^2$. [2+2+2+2+2=10 pts.]

- (a) Find ∇f .
- (b) Find the rate of change of f at the point $(1, 1, 1)$ in the direction of the position vector \mathbf{r} . (*Caution:* \mathbf{r} is not a unit vector.)
- (c) Find the rate of change of f at the point $(1, 1, 1)$ in the direction of most rapid increase of f .
- (d) The level sets $f = \text{const.}$ are ellipsoids. Find the unit normal to the ellipsoid at the point $(1, 1, 1)$.
- (e) What is the angle between \mathbf{r} and the normal to the ellipsoid at $(1, 1, 1)$? Check that in the spherically symmetric case $a = b = c$ the angle is zero.

Solution: I'll use component notation.

- (a) $\nabla f = (2ax, 2by, 2cz)$.
- (b) At $\mathbf{r} = (1, 1, 1)$ we have $|\mathbf{r}| = \sqrt{3}$ so $\hat{\mathbf{r}} = (1, 1, 1)/\sqrt{3}$. Also $\nabla f = (2a, 2b, 2c)$. Hence the rate of change of f in the direction of the position vector is $\nabla f \cdot \hat{\mathbf{r}} = (2a, 2b, 2c) \cdot (1, 1, 1)/\sqrt{3} = (2/\sqrt{3})(a + b + c)$.
- (c) The gradient itself points in the direction of most rapid increase. The rate of change in this direction is just the magnitude of the gradient, $2\sqrt{a^2 + b^2 + c^2}$.
- (d) The gradient is normal to the level sets (surfaces of constant value) of a function. Hence the unit normal is the gradient divided by its norm, $\hat{\mathbf{n}} = (a, b, c)/\sqrt{a^2 + b^2 + c^2}$.
- (e) The angle between \mathbf{r} and the unit normal is the inverse cosine of $\hat{\mathbf{r}} \cdot \hat{\mathbf{n}} = (1, 1, 1) \cdot (a, b, c)/(\sqrt{3}\sqrt{a^2 + b^2 + c^2}) = (a + b + c)/(\sqrt{3}\sqrt{a^2 + b^2 + c^2})$. This is equal to 1 when $a = b = c$, so the angle is zero.

3. Derive the following identities [2+2=4 pts]:

(a) If f is a scalar field and \mathbf{v} is a vector field then

$$\nabla \cdot (f\mathbf{v}) = \nabla f \cdot \mathbf{v} + f\nabla \cdot \mathbf{v}. \quad (1)$$

Solution: This is a direct consequence of the product rule for derivatives, together with linearity of the derivative:

$$\nabla \cdot (f\mathbf{v}) = \partial_x(fv_x) + \partial_y(fv_y) + \partial_z(fv_z) \quad (2)$$

$$= (\partial_x f)v_x + (\partial_y f)v_y + (\partial_z f)v_z + f(\partial_x v_x + \partial_y v_y + \partial_z v_z) \quad (3)$$

$$= \nabla f \cdot \mathbf{v} + f\nabla \cdot \mathbf{v}. \quad (4)$$

(b) If f is a scalar field and h is a function of one variable, then

$$\nabla h(f) = h'(f)\nabla f. \quad (5)$$

Solution: Let's check the x component:

$$\left(\nabla h(f)\right)_x = \partial_x(h(f)) = f'(h)\partial_x h = f'(h)(\nabla h)_x.$$

4. In this problem r and \mathbf{r} are the distance and the position vector from the origin. [20 pts.]

(a) (i) Show using both cartesian and spherical coordinates that $\nabla r = \hat{\mathbf{r}}$. (ii) Explain why this is dimensionally balanced. (iii) Derive this equation by a geometrical discussion of the properties of the direction and magnitude of ∇r . [(2+2)+2+2=8 pts.]

Solution: (i) Cartesian: $\nabla r = \partial_x r \hat{\mathbf{x}} + \dots = (x/r) \hat{\mathbf{x}} + \dots = (1/r)\mathbf{r} = \hat{\mathbf{r}}$. Spherical: $\nabla r = \partial_r r \hat{\mathbf{r}} = \hat{\mathbf{r}}$. (ii) Both sides are dimensionless: $\nabla \sim L^{-1}$ and $r \sim L$ so $\nabla r \sim 1$. On the other side, $\hat{\mathbf{r}} = (1/r)\mathbf{r} \sim L^{-1}L^1 \sim 1$ as well.

(b) Show that $\nabla \cdot \mathbf{r} = 3$. [2 pts.]

Solution: Using Cartesian coordinates, $\nabla \cdot \mathbf{r} = \partial_x x + \partial_y y + \partial_z z = 3$. Alternatively, using spherical coordinates, $\nabla \cdot \mathbf{r} = r^{-2} \partial_r (r^2 r) = 3$.

(c) Show that $\nabla \cdot \hat{\mathbf{r}} = 2/r$ by the following method: write $\hat{\mathbf{r}} = r^{-1}\mathbf{r}$, and use the results of problem 3 and problem 4b. [2 pts.]

Solution: $\nabla \cdot \hat{\mathbf{r}} = \nabla \cdot (r^{-1}\mathbf{r}) = -r^{-2} \nabla r \cdot \mathbf{r} + r^{-1} \nabla \cdot \mathbf{r} = -r^{-2} \hat{\mathbf{r}} \cdot \mathbf{r} + 3r^{-1} = -r^{-1} + 3r^{-1} = 2r^{-1}$.

(d) Show that if \mathbf{m} is a constant vector, then (i) $\nabla(\mathbf{m} \cdot \mathbf{r}) = \mathbf{m}$ and (ii) $\nabla(\mathbf{m} \cdot \hat{\mathbf{r}}) = r^{-1}(\mathbf{m} - (\mathbf{m} \cdot \hat{\mathbf{r}})\hat{\mathbf{r}})$. [2+2=4 pts.]

Solution: (i) $\nabla(\mathbf{m} \cdot \mathbf{r}) = \partial_x(m_x x + m_y y + m_z z) \hat{\mathbf{x}} + \dots = m_x \hat{\mathbf{x}} + \dots = \mathbf{m}$. (ii) $\nabla(\mathbf{m} \cdot \hat{\mathbf{r}}) = \nabla(r^{-1} \mathbf{m} \cdot \mathbf{r}) = -r^{-2} \mathbf{m} \cdot \mathbf{r} \nabla r + r^{-1} \mathbf{m} = r^{-1}(\mathbf{m} - (\mathbf{m} \cdot \hat{\mathbf{r}})\hat{\mathbf{r}})$.

- (e) The magnetic field of a dipole moment \mathbf{m} is $\mathbf{B}(\mathbf{r}) = (3(\mathbf{m} \cdot \hat{\mathbf{r}})\hat{\mathbf{r}} - \mathbf{m})/r^3$. Use the above results to show that this has zero divergence (as does *any* magnetic field satisfying Maxwell's equations). (The textbook does this using the explicit cartesian components of \mathbf{B} for the case $\mathbf{m} = m\hat{\mathbf{z}}$.) [4 pts.]

Solution: To make this more useful, and a little easier to follow, note first that $\hat{\mathbf{r}} \cdot \nabla(\mathbf{m} \cdot \hat{\mathbf{r}}) = 0$, so we can omit this term in evaluating $\nabla \cdot \mathbf{B}$. This is “obvious” once you think about it, since $\hat{\mathbf{r}}$ does not change along the $\hat{\mathbf{r}}$ direction. This is verified computationally, using the result of the previous part: $\nabla(\mathbf{m} \cdot \hat{\mathbf{r}}) \cdot \hat{\mathbf{r}} = r^{-1}(\mathbf{m} - (\mathbf{m} \cdot \hat{\mathbf{r}})\hat{\mathbf{r}}) \cdot \hat{\mathbf{r}} = 0$. Thus

$$\nabla \cdot \mathbf{B} = \nabla \cdot [r^{-3}(3(\mathbf{m} \cdot \hat{\mathbf{r}})\hat{\mathbf{r}} - \mathbf{m})] \quad (6)$$

$$= -3r^{-4}\hat{\mathbf{r}} \cdot (3(\mathbf{m} \cdot \hat{\mathbf{r}})\hat{\mathbf{r}} - \mathbf{m}) + 3r^{-3}(\mathbf{m} \cdot \hat{\mathbf{r}})\nabla \cdot \hat{\mathbf{r}} \quad (7)$$

$$= -6r^{-4}\mathbf{m} \cdot \hat{\mathbf{r}} + 6r^{-4}(\mathbf{m} \cdot \hat{\mathbf{r}}) \quad (8)$$

$$= 0. \quad (9)$$

5. Problems 8.2a,b,c,d (*Gravitational field of a spherically symmetric mass*) For part (c) you may just sketch the graph. No careful plot is required. [2+2+4+2=10 pts.]

Solution: (a) Integrate both sides over a volume, and use Gauss' theorem to convert the volume integral of $\nabla \cdot \mathbf{g}$ to the surface integral in (8.4).

(b) With S a sphere of radius r the surface element is $d\mathbf{S} = \hat{\mathbf{r}} r^2 d\Omega$. With $\mathbf{g} = g(r)\hat{\mathbf{r}}$ we thus have $\mathbf{g} \cdot d\mathbf{S} = g(r)r^2 d\Omega$. Integrating over the sphere then yields $4\pi r^2 g(r) = -4\pi GM$, hence $g(r) = -GM/r^2$.

(c) Integrating over a sphere of radius $r < R$ yields (8.4) again, but in place of M we have the amount of the mass $M(r) = (r/R)^3 M$ lying inside the radius r : the fraction $(r/R)^3$ of the total volume times the total mass M . Thus we can just use (8.5), with the same replacement, yielding $g(r) = -GM(r/R)^3/r^2 = -GMr/R^3$. At $r = R$ this agrees with the result from part (b), $-GM/R^2$. The plot of $g(r)$ is a straight line with negative slope starting at 0 for $r = 0$ and decreasing linearly to $-GM/R^2$ at $r = R$. For $r > R$ the plot then rises, asymptotically approaching the axis.

(d) For the electric field the calculation is identical, apart from the constant factors. We get $\int_V \nabla \cdot \mathbf{E} dV = \oint_S \mathbf{E} \cdot d\mathbf{S} = (1/\epsilon_0) \int_V \rho dV$, which vanishes for a volume inside the hollow sphere. By spherical symmetry, we have $\mathbf{E} = E(r)\hat{\mathbf{r}}$, so the surface integral is $4\pi r^2 E(r)$. Since the surface integral vanishes, we infer that $E(r) = 0$, so the electric field vanishes.