

Non-abelian (global) symmetries:
elementary group theory "motivated"

by non-trivial pion-nucleon system
(both fields transform)

- Nucleon (N) doublet, made of proton
(p) & neutron (n), assumed degenerate

$$(m_p = m_n \equiv m_N)$$

← real scalars

- Pion triplet: ϕ_i ($i = 1, 2, 3$) or in
terms of electric charge eigenstates
(see later): $\pi^0 \equiv \phi_3$ & $\pi^\pm \equiv \frac{\phi_1 \pm i\phi_2}{\sqrt{2}}$,

also assumed to be degenerate: $\sqrt{2}$

$$m^2_{\pi^\pm} = m^2_{\pi^0} = m^2_{\phi_i} \equiv \mu^2$$

↑
complex
scalar

$$- \mathcal{L}_{\text{free}} = \bar{\Psi} (i \not{\partial} - m_N) \Psi +$$

← $\propto \mathbb{1}_{2 \times 2}$

$$\frac{1}{2} (\partial_\mu \Phi)^T (\partial^\mu \Phi) - \frac{1}{2} \mu^2 \Phi^T \Phi, \text{ where}$$

$$\Psi \equiv \begin{pmatrix} \psi_p \\ \psi_n \end{pmatrix} \quad \& \quad \Phi = \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \end{pmatrix},$$

with $\mathcal{L}_{int} = -\frac{1}{4} \lambda (\underline{\Phi}^T \underline{\Phi})^4$ } pions
 } self-coupling

+ (π - N interaction, which is focus here)

$i g (\overline{\Psi} \gamma_5 \sigma \Psi) \cdot \underline{\Phi}$ (compactly)

Just to be explicit,

$(\overline{\Psi} \gamma_5 \sigma \Psi) \cdot \underline{\Phi} = \sum_{a=1,2,3} (\overline{\Psi} \gamma_5 \sigma_a \Psi) \phi_a$

"row" in triplet ϕ -space, but number in both Dirac and doublet N -spaces

$= \sum_a (\psi_p^+ \gamma_0 \gamma_5, \psi_n^+ \gamma_0 \gamma_5) \sigma_a \begin{pmatrix} \psi_p \\ \psi_n \end{pmatrix} \phi_a$ 2x2

$= \sum_a \sum_{ij} \sum_{\alpha, \beta} \Psi_{i\beta}^+ (\gamma_0 \gamma_5)_{\beta\alpha} (\sigma_a)_{ij} \Psi_{j\alpha} \phi_a$

triplet [ϕ] \rightarrow a
 doublet (N) \rightarrow ij
 Dirac \leftarrow α, β

... in particular, it contains $\overline{\Psi}_p \gamma_5 \Psi_n \pi^+$, i.e.,
 creates p annihilates π^+

p - n - π^+ coupling (γ_5 , i.e., pseudo-scalar based on that observation)

- what are (global) symmetries of above \mathcal{L} ?

(a combination of which is gauged/made local by adding photon field: see later)

(1) (Simple) Baryon-number [$U(1)_B$], i.e.,

$$\underline{\Phi} \rightarrow \underline{\Phi} \quad (\pi\text{'s are mesons) and}$$

$$\underline{\Psi} \rightarrow e^{i\theta} \underline{\Psi} \quad (B = +1 \text{ for both } p, n)$$

(2). (Non-trivial/more interesting) $SU(2)$

$SU(2)$ on $\underline{\Psi}$ and $SO(3)$ on $\underline{\Phi}$:

(a). $SU(2)$ on $\underline{\Psi}$ (as before):

$$\underline{\Psi} \rightarrow \tilde{U} \underline{\Psi} = \exp\left(-i \sum_{a=1,2,3} \beta_a \frac{\sigma_a}{2}\right) \underline{\Psi}$$

no $\mathbb{1}$, since $SU(2)$

(b). $SO(3)$ [to be explained below] on $\underline{\Phi}$:

$$\underline{\Phi} \text{ (column with 3 rows)} \rightarrow \exp\left(-i \sum_{a=1,2,3} \beta_a T_{adj}^a\right) \underline{\Phi}$$

where T_{adj}^a are 3×3 (hermitian) matrices ("adj." is for adjoint representation: see later):

$$T_1^{\text{adj.}} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & +i & 0 \end{pmatrix}; T_2^{\text{adj.}} = \begin{pmatrix} 0 & 0 & +i \\ 0 & 0 & 0 \\ -i & 0 & 0 \end{pmatrix} \& T_3^{\text{adj.}} = \begin{pmatrix} 0 & -i & 0 \\ +i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Note: $T_3^{\text{adj.}}$ eigenvectors are $(0\ 0\ 1)^T$, i.e., $\phi_3 (= \pi^0)$ and $(1, \pm i, 0)/\sqrt{2}$, i.e., $\pi^\pm [= (\phi_1 \pm i\phi_2)/\sqrt{2}]$, i.e., 2 of basis vectors $(0\ 1\ 0)$ & $(1\ 0\ 0)$ are **not** $T_3^{\text{adj.}}$ eigenvectors

[Later, we will mention another "basis" for generating same transformation]

- Now, $(i T_{\text{adj.}}^a)$ are anti-symmetric, real matrices forming a complete set (since these must be purely off-diagonal, of which there are 3 elements) $\Rightarrow R = \exp(-i \beta_a T_{\text{adj.}}^a)$ are 3×3 orthogonal matrices [sanity check: $R = \exp A$, where $A = -i \beta_a T_{\text{adj.}}^a$ is

anti-symmetric so that

$$R^T = \exp A^T = \exp(-A) \Rightarrow R^T R = \mathbb{1}]$$

And, $\det R = 1$, so called $SO(3)$ transformation (special, orthogonal in 3 dimensions)

[Aside: $\Phi \rightarrow -\Phi$ is not $SO(3)$, since transformation matrix = $-\mathbb{1}$ has determinant -1]

-Of course, $R = e^{iB}$ are also unitary, since $B = -\sum_a \beta_a T_{adj}^a$ are hermitian, but above is not really $SU(3)$ transformation, since T_{adj}^a 's above are (obviously) not complete set of hermitian matrices, which would be $9 = 3^2$ of them, "rest" of those give $[i T_a^{rest}]$ as complex, thus cannot "act" on real Φ (i.e., one would need three complex scalars to undergo full $SU(3)$ transformations

- In HW 5.1, check above is symmetry of full Lagrangian (free part and Φ self-coupling is easy, so π -N coupling is the real work here) ... + Noether's theorem...

Actually, are the different "looking" transformations on Ψ (2 dimensional, complex) vs. Φ (real, 3 dimension) related, just different realizations of same symmetry ?!

- Indeed, such a "unified" description might be suggested by number of generators being same for the 2 transformations (i.e., three of σ 's and above $T_{adj.}^a$'s) ...

... and (recall Phys 622!) how rotations in real/physical 3 d are implemented: by 3×3 orthogonal matrices acting on (3d) real vectors ("like" Φ here, but

in field space) vs. 2×2 unitary matrices on 2-component spinors (spin- $1/2$ system) ("like" Ψ here, but in p, n field space) ...

So, we resort to a more systematic approach (mathematical character of these transformations), i.e.,

elementary group theory ...

... which will show that above are two representations of same, $SU(2)$ [called isospin] symmetry: we can then generalize this to $SU(n)$

- Each set of transformation of fields given above forms a "group"

- Group: set of elements/objects with a multiplication operation ($x \circ y$) such that (i). $x \circ y$ belongs to set (for

every choice of x, y ; (ii) there exists
"identity" element: $(x \circ \mathbb{1}) = (\mathbb{1} \circ x) = x$;
(iii) "inverse" of every element: $x^{-1} \circ x = x \circ x^{-1} = \mathbb{1}$
and (iv) multiplication is associative:

$$(x \circ y) \circ z = x \circ (y \circ z)$$

- For transformations relevant to physics
(e.g. of fields or physical coordinates), "identity"
is "no" transformation; "multiplication"
is doing one transformation after
another etc.

- Specifically, for (internal) symmetry
transformations of fields, we used
matrix representations above: we can
easily check that $U(n)$ ($n \times n$ unitary)
matrices form a group, e.g., $U_1 U_2$ is also
unitary; $[U(n)]^{-1} = [U(n)]^{\dagger} \dots$

... similarly 3×3 orthogonal matrices (R)...

- Transformations of coordinates:
Lorentz "rotations" have matrix form, but

space-time translations do not quite ($x_\mu \rightarrow x_\mu + a_\mu$)

- Here, we will restrict to matrices...

...back to why $SO(3)$ is related to $SU(2)$:

number of group elements in continuous symmetry is ∞ , but can be represented by finite number of continuous parameters, e.g., θ for $U(1)$; β_a , where $a = 1, 2 \dots n^2$ for $U(n)$...

- Generators of group (T^a) are defined by group elements infinitesimally close to $\mathbb{1}$, i.e., $(\mathbb{1} - i\beta_a T^a)$ (β_a small) (T^a is analog of charge for non-abelian group) such that general group element is $\exp(-i\beta_a T^a)$, where β_a need not be small: this holds for $U(n)$, $SO(n)$... called Lie groups

- generators must satisfy certain properties in order to reproduce correct group multiplication, e.g., we can be motivated by generators of $SU(2)$, i.e., $\sigma^a/2$ which

form a closed algebra under commutation relations : $[\sigma_{a/2}, \sigma_{b/2}] = i \epsilon_{abc} (\sigma_{c/2})$

- Indeed, in general, if

$$[T_a, T_b] = i f_{abc} T_c,$$

then $\exp(-i \beta_a T^a)$ form a group, since

$e^A e^B$ (where A, B are of $-i \beta_a T^a$ form)

= (using Baker-Campbell-Hausdorff formula)

$$\exp \left\{ A + B + \frac{1}{2} \underbrace{[A, B]}_C + \frac{1}{12} \left(\underbrace{[A, \underbrace{[A, B]}_C]}_D - \underbrace{[B, \underbrace{[A, B]}_C]}_E \right) + \dots \right\}$$

$$= \exp(A + B + \dots C + \dots D + \dots E + \dots)$$

(where C, D, E are same form as A, B due to commutation relations of T^a 's)

= same form as e^A, e^B , i.e.,

$$\exp[-i \beta_a^{(1)} T^a] \times \exp[-i \beta_b^{(2)} T^b] = \exp[-i \beta_c^{(3)} T^c]$$

- Thus, group is "defined" by commutation relations of its generators (Lie algebra), e.g.,

(1). $SU(2)$ acting on doublet $\underline{\psi}$: $T^a = \frac{\sigma^a}{2}$ ($a=1,2,3$)

with $[\sigma_{a/2}, \sigma_{b/2}] = i\epsilon^{abc}(\sigma_{c/2})$

- clearly f_{abc} (called structure constants) = $-f_{bac}$, i.e.,

antisymmetric in a, b (following from commutation relations;

$$[T_b, T_a] = -[T_a, T_b] = -if_{abc} T^c = +if_{bac} T^c$$

- Furthermore, T^a 's can be chosen such that f_{abc} is totally anti-symmetric: $f_{abc} = -f_{acb} = -f_{cba}$,

e.g., ϵ_{abc} for $SU(2)$ above

- Remarkably,

(2). $SO(3)$ on (real) triplet $\underline{\Phi}$ has

Lie algebra identical to $SU(2)$:

$$[T_{adj}^a, T_{adj}^b] = i \epsilon_{abc} T_{adj}^c$$

i.e., $[T^a, T^b] = i \epsilon_{abc} T^c$ for

$T_a = \sigma_{a/2}$ (2×2 matrices: traceless & hermitian)

& T_a^{adj} , where $i T_a^{adj}$ are

real, antisymmetric (3×3) matrices

\Rightarrow elements of group generated by T_a^{adj}

(i.e., 3×3 orthogonal matrices, with determinant 1) are in one-to-one

correspondence with those generated

by $\sigma_{a/2}$ (2×2 unitary matrices, with determinant 1). Namely, if we have

$$\exp\left[-i\beta_a^{(1)} \frac{\sigma_a}{2}\right] \times \exp\left[-i\beta_b^{(2)} \frac{\sigma_b}{2}\right] = \exp\left[-i\beta_c^{(3)} \frac{\sigma_c}{2}\right],$$

product of 2 group elements:
2 x 2 unitary matrices

another group
element

then (i.e., necessarily) we have for 3×3 orthogonal matrices,

$$\exp[-i\beta_a^{(1)} T_a^{\text{adj}}] \times \exp[-i\beta_b^{(1)} T_b^{\text{adj}}] = \exp[-i\beta_c^{(3)} T_c^{\text{adj}}]$$

[i.e., same 3 β_a 's for both group element multiplications]

- We say $SU(2)$ is isomorphic to $SO(3)$ or these are simply 2 different representations of $SU(2)$: doublet/fundamental and triplet/adjoint...

\Rightarrow π -N system has just one non-abelian symmetry, i.e., $SU(2)$: it's just that π , N transform as different representations under it (again doublet for Ψ vs. triplet for Φ)

- We will generalize above 2 representations to $SU(n)$, but before that, a couple of more comments on the example above:

- we can **gauge** a subgroup of global symmetry of π - N system, i.e., $SU(2)_{\text{isospin}} \times U(1)_B$, by coupling to EM field: see separate note [later on, we will find something similar with the full electro-weak gauge group, i.e., $U(1)_{EM}$ is a sub-group of $SU(2)_L \times U(1)_Y$]

- Another basis for generators of adjoint (or triplet) representation of $SU(2)$ is given by (see ϵL p. 93):

$$J_3 \propto \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}; J_1 \propto \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \& J_2 \propto \begin{pmatrix} 0 & -i & 0 \\ +i & 0 & -i \\ 0 & +i & 0 \end{pmatrix}$$

\Rightarrow basis vectors $(1\ 0\ 0)^T$, $(0\ 1\ 0)^T$ & $(0\ 0\ 1)^T$ are eigenvectors of J_3 with eigenvalues $+1$, 0 & -1 (respectively), with $\underline{J_+} = \underline{J_1 + i J_2}$ being

raising/lowering operators for J_3 eigenvalue:

$$J_+ \propto \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \& J_- \propto \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

(One can check that $[J_a, J_b] = i \epsilon_{abc} J_c$,

as is familiar from angular momentum theory)

- In this basis $\pi^0 \sim (0 \ 1 \ 0)^T$ (T_3 eigenvalue 0), while $(1 \ 0 \ 0)^T$ & $(0 \ 0 \ 1)^T$ are π^\pm ,

with T_3 eigenvalues ± 1 (respectively)

... cf. earlier basis, i.e., generators T_a^{adj} .

being (imaginary) anti-symmetric 3×3

matrices so that group elements $\exp[-i\beta_a T_a^{\text{adj}}]$ are orthogonal (real) matrices; T_3^{adj}

eigenvectors are $(0 \ 0 \ 1)^T$ & $(1 \pm i \ 0)^T / \sqrt{2}$

with eigenvalues 0 (i.e., π^0) & ± 1 (i.e., π^\pm)

(respectively)

- The 2 bases are related by a "similarity transformation": this could be useful in HW (e.g.

- in a different context - is in Eq. 4.72 of CL)

- Onto $SU(n)$, where

(1). **fundamental** (n -dimensional) representation was already studied earlier: generators,

T_{fund}^a , are $(n \times n)$ traceless hermitian

matrices, group elements are $(n \times n)$
unitary matrices with determinant 1 ...
acting on (complex) column vectors with n rows

- these T_{fund}^a can give us structure constants of $SU(n)$, i.e.,

$$\left[T_{\text{fund}}^a, T_{\text{fund}}^b \right] = i f_{abc} T_{\text{fund}}^c, \text{ where}$$

f_{abc} can be chosen to be totally anti-symmetric

(2) adjoint representation: we can be "inspired" here by $SU(2)$, i.e., dimension of this representation [= 3 for $SU(2)$] is same as number of generators (which of course is same for all representations of a group) ... and T_{adj}^a can actually be "formed" out of structure constants: indeed, for $SU(2)$, we see that $(T_{\text{adj}}^a)_{bc} = i \epsilon_{abc}$
- So, in general, we can show

$$\left(T_{adj}^c \text{ [for } SU(n)] \right)_{ab} = -if_{abc}$$

$1 \dots (n^2 - 1)$
 (number of generators)

$(n^2 - 1) \times (n^2 - 1)$
 matrix (dimension of representation)

i.e., that above T_{adj}^a satisfy $SU(n)$

Lie algebra: see HW 5.2.1

... of course, we have "trivial" representation for any group (called

singlet), i.e., $T^a = 0$... so, only group element is $\mathbb{1}$ (no transformation)

& other representations (matrices acting on column vectors of other dimensions), but we won't need beyond above 3 here

[In general, representation of group, i.e., elements, need not be matrices and "multiplication" might actually be "addition", e.g., integers: $\mathbb{1}$ is "0", inverse of integer is its negative ...]