

Lecture 16, Oct. 7 (Wed.)

Outline for today (& part of Fri.)

- finish PI approach to QM:
 - Feynman's ansatz for (infinitesimal) transition amplitude
 - justification: (1) recover (earlier) propagator for small (time) segment; (2) get classical path as $\hbar \rightarrow 0$; (3) satisfies Schrödinger's time-dependent wave equation

x

Feynman's "intuition": for each (small) segment of path, assign

$$\langle x_n, t_n | x_{n-1}, t_{n-1} \rangle \propto \exp\left[i S(n, n-1)/\hbar\right]$$

where $S_{n,n-1} = \int_{t_{n-1}}^{t_n} dt L_{\text{classical}}(x, \dot{x})$ (classical action)

More precisely (match dimensions):

$$\langle x_n, t_n | x_{n-1}, t_{n-1} \rangle = \frac{1}{W(\Delta t)} \exp\left[i S(n, n-1)/\hbar\right]$$

\uparrow
 $\sim 1/\text{length}$ weight factor

1st (sanity) check : recover, for small Δt .

free-particle propagator of earlier:

$$K_{\text{free}}(x'', t''; x', t') = \langle x'', t'' | x', t' \rangle$$

$$= \sqrt{\frac{m}{2\pi i\hbar(t''-t')}}$$

$$\exp\left[\frac{i m (x'' - x')^2}{2\hbar(t'' - t')}$$

$$S(n, n-1) = \int_{t_{n-1}}^{t_n} \left\{ \frac{1}{2} m \dot{x}^2 - V(x) \right\} dt$$

$$\approx \Delta t \left[\frac{1}{2} m \left(\frac{x_n - x_{n-1}}{\Delta t} \right)^2 - V \left(\frac{x_n + x_{n-1}}{2} \right) \right]$$

$$\Rightarrow \langle x_n, t_n | x_{n-1}, t_{n-1} \rangle = \frac{1}{w(\Delta t)} \exp\left[\frac{i m (x_n - x_{n-1})^2}{2\hbar \Delta t}\right]$$

a la Feynman
"reproduces" $\exp \dots$ of earlier propagator

$$\Rightarrow \frac{1}{w(\Delta t)} = \sqrt{\frac{m}{(2\pi i\hbar \Delta t)}} \quad \begin{array}{l} \text{"matching" pre-factors} \\ \text{(but related)} \end{array}$$

[see Sakurai for alternate way to get $w(\Delta t)$, by only requiring Feynman's amplitude gives $\delta(x_n - x_{n-1})$ as $\Delta t \rightarrow 0$]

So, **Feynman's proposal**:

$$\langle x_n, t_n | x_{n-1}, t_{n-1} \rangle = \sqrt{\frac{m}{2\pi i\hbar \Delta t}} \exp\left[\frac{i S(n, n-1)}{\hbar}\right]$$

2nd (sanity) check: for finite $(t_N - t_1)$, only classical path relevant as $\hbar \rightarrow 0$

- Using $\langle x_n, t_n | x_{n-1}, t_{n-1} \rangle = \sqrt{\frac{m}{2\pi i \hbar \Delta t}} \exp[i S(n, n-1)/\hbar]$

for each segment of path (choice of $x_{N-1}, x_{N-2} \dots x_2$), we get

$$\langle x_N, t_N | x_1, t_1 \rangle = \lim_{\substack{N \rightarrow \infty \\ (\Delta t \rightarrow 0)}} \left(\frac{m}{2\pi i \hbar \Delta t} \right)^{\frac{N-1}{2}} \text{ weight factors}$$

(total) transition amplitude
 ala Feynman

$\int dx_{N-1} \int dx_{N-2} \dots \int dx_2$
 "sum" over paths

$\prod_{n=2}^N \exp \left[\frac{i S(n, n-1)}{\hbar} \right]$
 (product)

transition amplitude for
segment of path

Compact notation:

$$\int_{x_1}^{x_N} \delta[x(t)] = \lim_{N \rightarrow \infty} \left(\frac{m}{2\pi i \hbar \Delta t} \right)^{\frac{N-1}{2}} \int dx_{N-1} \dots \int dx_2$$

$\Delta t = (t_N - t_1)/(N-1)$

$$\text{Also, } \prod_{n=2}^N \exp\left[\frac{iS(n,n-1)}{\hbar}\right] = \exp\left[i\sum_{n=2}^N S(n,n-1)\right] = e^{i \frac{S(N,1)}{\hbar}}$$

action
 for (full) path

$$\langle x_N, t_N | x_1, t_1 \rangle = \int_{x_1}^{x_N} D[x(t)] \exp\left[i \int_{t_1}^{t_N} dt L_{\text{classical}}(x, \dot{x})\right]$$

$$\sim \sum_{\text{path}} \exp\left(i S_{\text{path}} / \hbar\right)$$

— For given path, contributions from neighboring paths (S different, even if slightly) as

$\hbar \rightarrow 0$ cancel each other (due to $\exp(iS/\hbar)$)
oscillations

... except for path which is extremum of S :
 $\delta S = 0$ (classical path!) ... $\Rightarrow S_{\text{neighbor}} = S_{\text{min.}} \text{ (classical)}$

\Rightarrow contributions add-up ...

\Rightarrow as $\hbar \rightarrow 0$, sum over paths dominated by classical path (as desired)

Alternative (to Schroedinger equation)
 formulation, based on (a) superposition principle (sum over paths); (b) composition property of transition amplitude and (c)
 reproduce classical path as $\hbar \rightarrow 0$

3rd check : for $V \neq 0$, show that Feynman's formula for $\langle x_N, t_N | x_1, t_1 \rangle$ satisfies Schrödinger time-dependent wave equation, i.e., same as propagator, $K(x_N, t_N; x_1, t_1)$ before

— since we want $\frac{\partial}{\partial t}$ of $\langle x_N, t_N | x_1, t_1 \rangle$, "split" it into large t_1 to t_{N-1} and small t_{N-1} to t_N ("final") intervals:

$$\langle x_N, t_N | x_1, t_1 \rangle = \int dx_{N-1} \langle x_N, t_N | x_{N-1}, t_{N-1} \rangle \times \langle x_{N-1}, t_{N-1} | x_1, t_1 \rangle$$

— Use notation: $\xi = x_N - x_{N-1}$; $x_N \rightarrow x$; $t_{N-1} \rightarrow t$
 $t_N = t + \Delta t$ (Δt small, but ξ can be large so far: see below)

so that

$$\langle x, t + \Delta t | x_1, t_1 \rangle = \int d\xi \langle x, t + \Delta t | x - \xi, t \rangle \times \langle x - \xi, t | x_1, t_1 \rangle$$

— For Δt small, we have 1st factor on RHS

$$\langle x, t + \Delta t | x - \xi, t \rangle = \sqrt{\frac{m}{2\pi i \hbar \Delta t}} \quad \begin{cases} \text{weight } x \\ \text{factor} \end{cases}$$

$\alpha \text{ la Feynman}$

$$\exp \left[i \frac{m}{2\hbar} \frac{\xi^2}{\Delta t} - i \int_t^{t+\Delta t} dt V \left(\text{between } x \text{ & } x - \xi \right) \right]$$

$i \frac{s_{N,N-1}}{\hbar}$

$$= \int \frac{(x_N - x_{N-1})^2}{(\Delta t)^2} dt$$

$$= \int dt \dot{x}^2$$

from
 \cancel{x} ^{1st} factor

- Use $\lim_{\Delta t \rightarrow 0} \sqrt{\frac{m}{2\pi i \hbar \Delta t}} \exp \left(i \frac{m \xi^2}{2\hbar \Delta t} \right) = \boxed{\delta(\xi)}$

so that $\int d\xi \dots$ dominated by ξ small

\Rightarrow two expansions \cancel{x} factor
(2^{nd} factor)

(a) $\langle x - \xi, t | x_i, t_i \rangle$ and $V \left(\text{between } x \text{ & } x - \xi \right)$

in powers of ξ , but drop ξ^{odd} , since

$x \exp \left[i \frac{m \xi^2}{2\hbar \Delta t} \right] (\text{even power of } \xi) \dots$

$$\Rightarrow \int d\xi \dots \rightarrow 0$$

(b). expand for small Δt on LHS and

in $\exp\left[i/\hbar \int_t^{t+\Delta t} dt V\right]$ in 1st RHS ... to give factor

$$\langle x, t | x_1, t_1 \rangle + \frac{\Delta t}{\hbar} \frac{\partial}{\partial t} \langle x, t | x_1, t_1 \rangle = + \Delta t^2 \dots$$

$$\sqrt{\frac{m}{2\pi i \hbar \Delta t}} \int d\xi \exp\left[\frac{i m \xi^2}{2 \hbar \Delta t}\right] \times \text{RHS 1st factor}$$

$$\left[\begin{array}{c} 1 \\ \uparrow \\ \text{call it term} \end{array} - \frac{i}{\hbar} \frac{\Delta t}{\hbar} V(x) - \frac{i}{\hbar} \Delta t \frac{\xi^2}{2} \frac{\partial^2}{\partial x^2} V(x) \right] \xrightarrow{\text{drop } \xi^1} \text{RHS 2nd factor}$$

$$\left[\begin{array}{c} 4 \\ \langle x, t | x_1, t_1 \rangle + \frac{\xi^2}{2} \frac{\partial^2}{\partial x^2} \end{array} \langle x, t | x_1, t_1 \rangle \right]$$

- Use $\int d\xi \sqrt{\frac{m}{2\pi i \hbar \Delta t}} \exp\left[\frac{i m \xi^2}{2 \hbar \Delta t}\right] = 1$ to

(i). cancel leading terms [not $\propto \Delta t, \xi^2$]

on both sides [4×1 on RHS] ... and

(ii). in evaluating 4×2

- Use $\sqrt{\frac{m}{2\pi i \hbar \Delta t}} \int d\xi \xi^2 \exp[i m \frac{\xi^2}{2\hbar \Delta t}] = \frac{i\hbar}{m} \Delta t$
 to evaluate $\textcircled{4} \times \textcircled{3}$ and $\textcircled{5} \times \textcircled{2}$
- We then get
- $$\frac{\Delta t \frac{\partial}{\partial t} \langle x, t | x_1, t_1 \rangle = -\frac{i}{\hbar} v(x) \Delta t \textcircled{4} \times \textcircled{2}}{+ \left(\frac{i\hbar}{m} \right) \left(\frac{i}{2\hbar} \right) (\Delta t)^2 \frac{\partial^2 v}{\partial x^2} \langle x, t | x_1, t_1 \rangle \textcircled{4} \times \textcircled{3}}$$
- $$+ \left(\frac{i\hbar}{2m} \right) \Delta t \frac{\partial^2}{\partial x^2} \langle x, t | x_1, t_1 \rangle \left[1 - \frac{i}{\hbar} v(x) \Delta t \right]$$

$$\textcircled{1} \times \textcircled{5} \quad \textcircled{5} \times \textcircled{2}$$
- drop Δt^2 as $\Delta t \rightarrow 0$ (keep only Δt^1)
- what about $\textcircled{5} \times \textcircled{3}$? It's even higher order in Δt (due to $\int d\xi \xi^4 \exp \dots$)
 $\dots \times (i\hbar) \times \frac{1}{\Delta t}$ gives (finally!)

$$i\hbar \frac{\partial}{\partial t} \langle x, t | x_1, t_1 \rangle = v(x) \langle x, t | x_1, t_1 \rangle - \frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} \langle x, t | x_1, t_1 \rangle$$

... as desired ...