

796

(1)

$$\begin{aligned}
 & V_x(x, y) dx + V_y(x+dx, y) dy - V_x(x, y+dy) dx - V_y(x, y) dy \\
 &= \cancel{V_x(x, y) dx} + V_y(x, y) dy + \frac{\partial V_y}{\partial x}(x, y) dx dy - \cancel{V_x(x, y) dx} - \frac{\partial V_x}{\partial y}(x, y) dx dy - \cancel{V_y(x, y) dy} \\
 &= (\partial_x V_y - \partial_y V_x) dx dy
 \end{aligned}$$

83a)

$$\vec{V} = f(y) \hat{x}$$



the flow is only in the x-direction, No matter where the particle starts, all it does is move to the right (so it can never return to it's original position).

83b)

$$\nabla \times \vec{V} = -\frac{\partial f}{\partial y} \hat{z}$$

83c)

$$\vec{V} = V_0 e^{-\frac{y^2}{L^2}} \hat{x}$$

$$\nabla \times \vec{V} = -V_0 \frac{\partial e^{-\frac{y^2}{L^2}}}{\partial y} \hat{z} = V_0 \left(\frac{2y}{L^2} \right) e^{-\frac{y^2}{L^2}} \hat{z}$$

and it is positive for the upper paddle wheel (since $y > 0$) and negative for the lower paddle wheel (since $y < 0$)

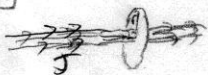
84d)

$$\vec{V} = \frac{A}{r} \hat{\phi}$$

$$\nabla \times \vec{V} = \left(\frac{\partial V_\phi}{\partial r} + \frac{V_\phi}{r} \right) \hat{z} = \left[-\frac{A}{r^2} + \frac{A}{r^2} \right] \hat{z} = 0$$



85a)



due to symmetry,
 $\vec{B} = B(r) \hat{\phi}$; $\vec{B}$ is a function of r , not ϕ or z

$$\vec{B} = f(r) \hat{\phi}$$

Away from wire $\nabla \times \vec{B} = 0$

$$\frac{\partial}{\partial r}(rf) = 0$$

$$f(r) = \frac{A}{r}$$

85b

We didn't use anything involving the magnitude of $\vec{B}$, only the direction (because in part a, we only looked in the region away from wire where $\nabla \times \vec{B} = 0$, and so we didn't use any info involving the magnitude of $\vec{B}$)

89a

$$\vec{v} = (x+y+z)\hat{z}$$



$$\begin{aligned}\oint_S \vec{v} \cdot d\vec{S} &= \int dS (x+y+z) \cos\theta \\ &= R^2 \int_0^{2\pi} \int_0^\pi [\sin\theta \cos\phi + \sin\theta \sin\phi + \cos\theta] \sin\theta \cos\theta \, d\phi \, d\theta \\ &= R^2 \int_0^{2\pi} \int_0^\pi \sin\theta \cos^2\theta \, d\theta \, d\phi \quad (2\pi) \\ &= -2\pi R^2 \sin\theta \\ &= -2\pi R^2 \left[\frac{\cos\theta}{3} \right]_0^\pi \\ &= \frac{4\pi R^2}{3}\end{aligned}$$

89b

$$\nabla \cdot \vec{v} = 1$$

$$\int_V (\nabla \cdot \vec{v}) \, dV = \int_V (1) \, dV = \frac{4}{3}\pi R^3$$

another 89a

$$\nabla \cdot \vec{g} = -4\pi G \rho \quad \text{eq. 6.33}$$

$$\int_V (\nabla \cdot \vec{g}) \, dV = -4\pi G \int_V \rho \, dV$$

$$\oint_S \vec{g} \cdot d\vec{S} = -4\pi G M$$

another 89b

$$\oint_S \vec{g} \cdot d\vec{S} = -4\pi G M$$

$$4\pi r^2 g = -4\pi G M$$

$$g(r) = -\frac{GM}{r^2}$$

$$\vec{g}(\vec{r}) = -\frac{GM}{r^2} \hat{r}$$

(3)

90c

$$\nabla \cdot \vec{g} = -4\pi G \rho$$

$$\int_V \nabla \cdot \vec{g} = - \int_V 4\pi G \rho$$

$$\oint_S \vec{g} \cdot d\vec{S} = - \int_V 4\pi G \rho$$

$$4\pi r^2 g = -4\pi G \int_V \rho$$

$$g = -\frac{G}{r^2} M \frac{r^3}{R^3}$$

$$\vec{g}(\vec{r}) = -\frac{GM}{R^3} \vec{r}$$

91d

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\oint_S \vec{E} \cdot d\vec{S} = \int_V \frac{\rho}{\epsilon_0}$$

$$4\pi r^2 E = 0$$

W.1

$$\nabla \times \vec{v} = \nabla \times [\vec{\omega} \times \vec{r}]$$

$$= \nabla \times (\omega_i x_j \hat{e}_k \epsilon_{ijk})$$

$$= \partial_i \omega_j x_k \epsilon_{ikm} \epsilon_{ijk} \hat{e}_m$$

$$= \omega_i \epsilon_{jkm} \epsilon_{ijk} \hat{e}_m \quad \partial_i \omega_j x_k \epsilon_{ikm} \hat{e}_m$$

$$= 2\delta_{mi} \omega_j \hat{e}_m$$

$$= 2\omega_i \hat{e}_i$$

$$= 2\vec{\omega}$$