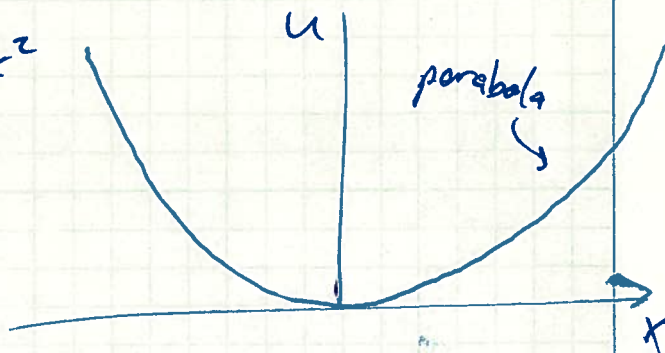


Exam 1 Review

Simple Harmonic Oscillator (no damping)
(no driving force)

$$F = -kx \Rightarrow U = \frac{1}{2} kx^2$$



Eg. of motion:

$$\ddot{x} + \frac{k}{m}x = 0$$

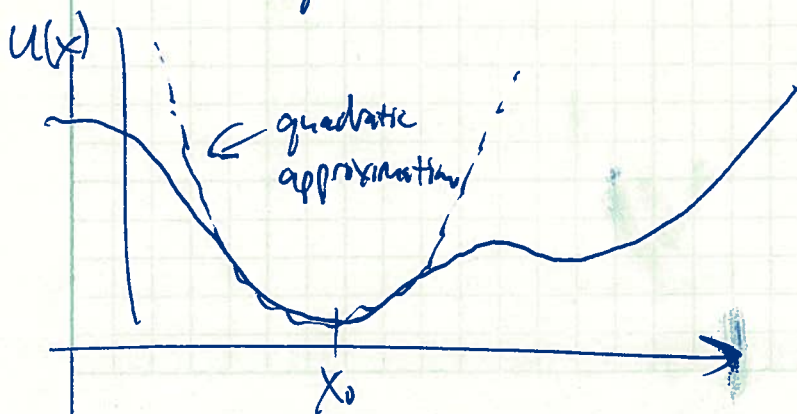
Defn $\omega_0^2 = k/m$
 Solution: $x = A e^{i(\omega_0 t + \delta)}$
 ↑
 natural frequency.

A, δ determined by initial conditions

Small Oscillations: Near a stable equilibrium, almost any potential function is approximately quadratic.

$$U(x_0 + a) \approx U(x_0) + U'(x_0)a + \frac{1}{2}U''(x_0)a^2 + \dots$$

↑ ↑ displacement equilibrium



$U'(x_0) = 0$ since x_0 is an equilibrium point.

②

$$\text{Frequency of small oscillations: } \omega_0 \approx \sqrt{\frac{U''(x_0)}{m}}$$

near an equilibrium.

$$\text{Plan Pendulum: } U = mgl(1 - \cos \theta)$$

$$\Rightarrow \omega_0 = \sqrt{g/l}$$

Complex Numbers

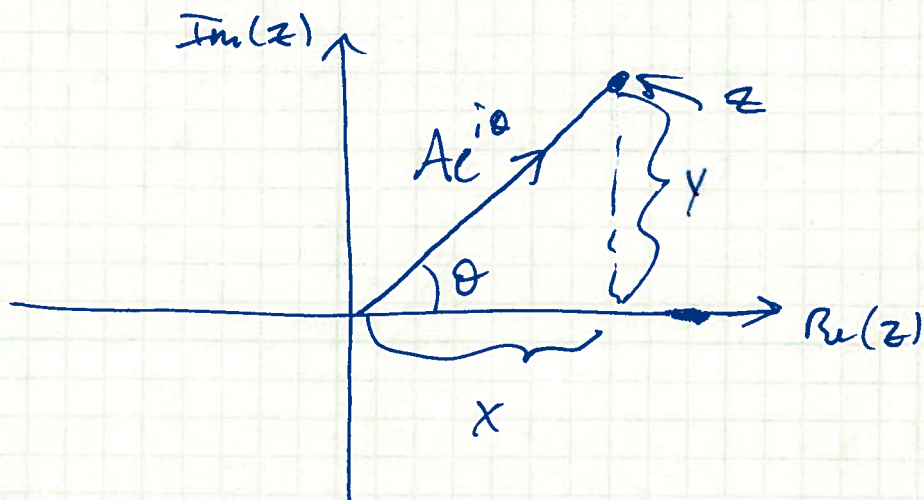
$$z = x + iy = Ae^{i\theta}$$

$$A = \sqrt{x^2 + y^2}, \quad \theta = \tan^{-1}(y/x)$$

$$x = A \cos \theta, \quad y = A \sin \theta$$

$$e^{i\theta} = \cos(\theta) + i \sin(\theta) \quad \text{Euler Formula}$$

$$x = \frac{e^{i\theta} + e^{-i\theta}}{2}, \quad y = \frac{e^{i\theta} - e^{-i\theta}}{2}$$



$$\ddot{x} + \gamma \dot{x} + \omega_0^2 x = \frac{F_0}{m} e^{i\omega t}$$

where $\gamma \equiv \frac{b}{m}$
 $\omega_0^2 = \frac{k}{m}$

Solution:

Steady-state (Long-term) Solution:

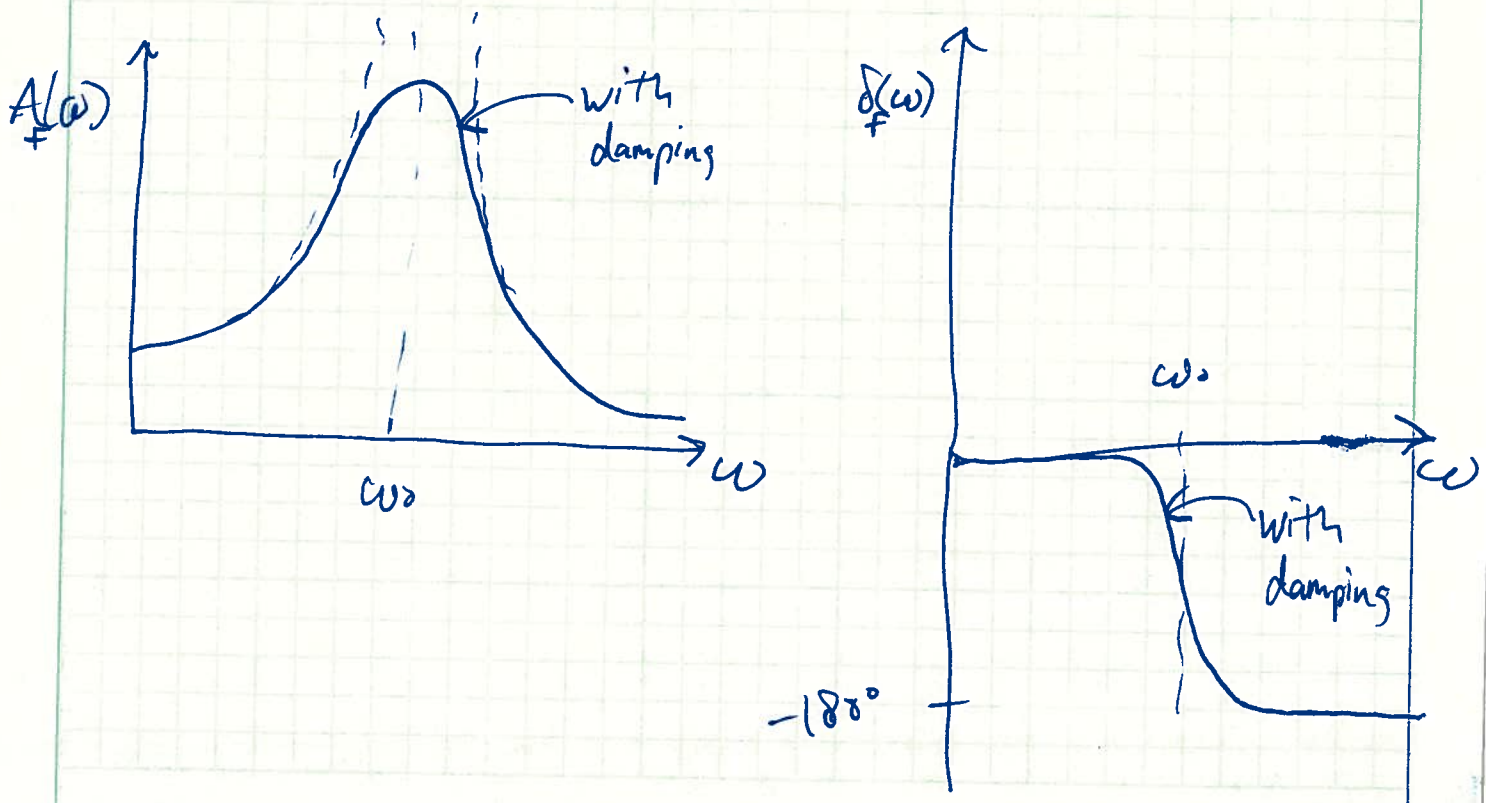
$$x(t) = A_{\neq}(\omega_{\neq}) e^{i(\omega_{\neq} t + \phi_{\neq}(\omega_{\neq}))}$$

no free parameters

where $A_{\neq}(\omega) = \frac{F_0/m}{\sqrt{(\omega_0^2 - \omega^2)^2 + (\omega\gamma)^2}}$

and $\phi_{\neq}(\omega) = -\tan^{-1} \left[\frac{\omega\gamma}{\omega_0^2 - \omega^2} \right]$

ω_{\neq} = driving frequency



(Short-term)

Including the transient solution (Short-term Behavior):

$$x(t) = A(\omega_f) e^{i(\omega_f t + \phi_f(\omega_f))} + B e^{-\gamma/2 t} e^{i(\omega_d t + \delta_d)}$$

$$\omega_d = \text{damped frequency} = \sqrt{\omega_0^2 - \gamma^2/4}$$

B & δ_d = Free parameters, determined by initial conditions.

Special case: Damped oscillator, no forcing function

Then $F_0 = 0$, $A(\omega_f) = 0$,

$$\text{and } x(t) = B e^{-\gamma/2 t} e^{i(\omega_d t + \delta_d)}$$

↑
damping factor

Energy

- Mechanical oscillators: $KE = \frac{1}{2} m \dot{x}^2$
 $U = \frac{1}{2} k x^2$

- Electrical oscillators: $U_E = \int_{\text{all space}} \frac{1}{2} \epsilon_0 |\vec{E}|^2 dV$

for capacitors $\rightarrow = \frac{1}{2} QV = \frac{1}{2} CV^2 = \frac{Q^2}{2C}$

$$U_B = \int_{\text{all space}} \frac{1}{2\mu_0} |\vec{B}|^2 dV$$

for inductors $\rightarrow = \frac{1}{2} LI^2$

Energy loss $Q = \frac{\omega_0}{\gamma} = \text{unitless}$ & very large for lightly damped oscillators.

For lightly damped oscillators

$$Q = \frac{\text{Fraction of energy lost in time } t = \frac{1}{\omega_0}}{\text{Fraction of energy loss in one period}} = \frac{2\pi}{\text{Fraction of energy loss in one period}}$$

Energy loss: $E(t) = E_0 e^{-\gamma t} = KE(t) + U(t)$ for mechanical oscillators
 $= U_E(t) + U_B(t)$ for electrical oscillators

AC circuits

Voltage rules:

$ V_C = \left \frac{1}{C} Q \right $	Capacitor
$ V_L = \left L \frac{dI}{dt} \right $	Inductor
$ V_R = IR $	Resistor

Simple LC circuit: $\omega_0 = \frac{1}{\sqrt{LC}}$ (simple harmonic oscillator)

Impedances:

$$Z_R = R$$

$$Z_L = i\omega L$$

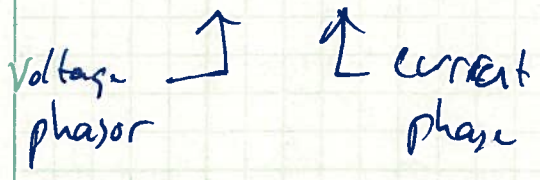
$$Z_C = \frac{-i}{\omega C}$$

Series Combination: $Z_{\text{series}} = Z_1 + Z_2$

Parallel Combination: $Z_{\text{parallel}} = \left[(Z_1)^{-1} + (Z_2)^{-1} \right]^{-1}$

For any element or combination of elements,

$$\vec{V} = \vec{I} Z \leftarrow \text{impedance, possibly complex.}$$



~~if~~ In general Z is complex, which means that there is a phase offset between \vec{V} & \vec{I} .

The ~~ratio~~ ratio of $\frac{V_0}{I_0} = |Z|$.

$$\vec{V}_L = \vec{I}_L (i\omega L)$$

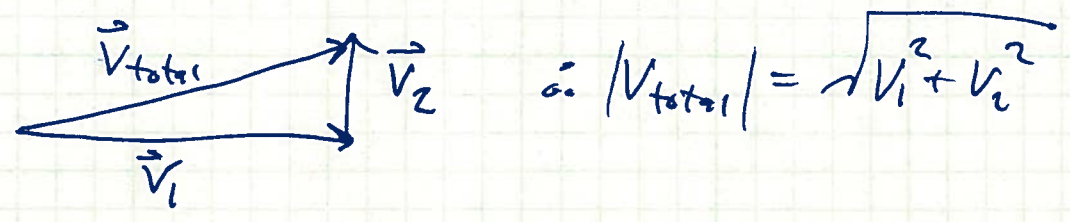
↑ this means V_L leads I_L by 90° .

$$\vec{V}_C = \vec{I}_C \left(\frac{-i}{\omega C}\right)$$

↑ this means V_C lags I_C by 90°

Phasor Diagrams show the geometric relationships between \vec{V} & \vec{I} for a circuit.

This can be very useful when combined with a sum rule like $\vec{V}_{total} = \vec{V}_1 + \vec{V}_2$ or $\vec{I}_{total} = \vec{I}_1 + \vec{I}_2$



Normal Mode: In a multi particle system, a normal mode is a type of motion where all particles oscillate at the same frequency.

- The number of normal modes is equal to the number of particles.
- Each normal mode goes at its own frequency.
- The general solution is a sum over normal modes:

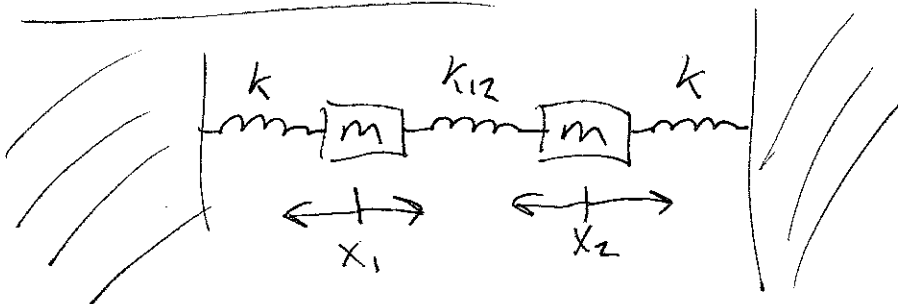
$$\vec{X}(t) = \sum_{n=1}^2 c_n \vec{q}_n e^{i\omega_n t}, \text{ for a 2 particle system.}$$

The expansion coefficients $\{c_n\}$ are determined by the initial conditions and can be calculated using "Fourier's Trick":

$$c_n \equiv a_n + ib_n, \quad a_n = \frac{\vec{x}_0 \cdot \vec{q}_n}{|\vec{q}_n|^2}, \quad b_n = \frac{-\vec{v}_0 \cdot \vec{q}_n}{\omega_n |\vec{q}_n|^2}$$

where \vec{q}_n are the normal mode eigenvectors and \vec{x}_0 and \vec{v}_0 are the initial position and velocity.

2 coupled oscillators



Two normal modes:

$$\vec{q}_1 = (1, 1) = \text{"symmetric mode"}$$

$$\vec{q}_2 = (1, -1) = \text{"anti-symmetric mode"}$$

Eqs. of Motion:

$$m\ddot{x}_1 + (k + k_{12})x_1 - k_{12}x_2 = 0$$

$$m\ddot{x}_2 + (k + k_{12})x_2 - k_{12}x_1 = 0$$

Solution:

$$(x_1(t), x_2(t)) = c_1 (1, 1) e^{i\omega_1 t} + c_2 (1, -1) e^{i\omega_2 t}$$

For this system we called

$$\omega_1 = \omega_{\text{small}} = \sqrt{k/m}$$

$$\omega_2 = \omega_{\text{large}} = \sqrt{\frac{k + 2k_{12}}{m}}$$