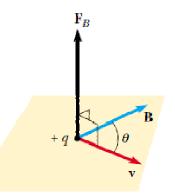
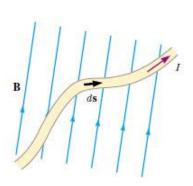
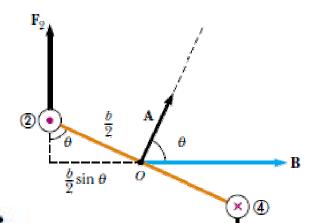
MIT visualizations: Biot Savart Law, Integrating a circular current loop on axis

#### Last time:

- -Moving charges (and currents) create magnetic fields
- -Moving charges (and currents) feel a force in magnetic fields
- $\mathbf{F}_B = q\mathbf{v} \times \mathbf{B}$  Defines the B-field; Examples cyclotron frequency, velocity selector,





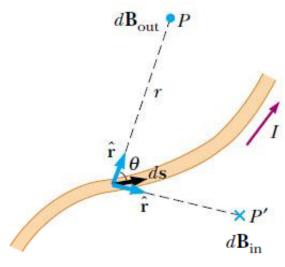


mass spectrometer

- Force on a wire segment:
- $\int_a a dx$
- Force on a straight wire segment in uniform B-field:
- $\mathbf{F}_B = I\mathbf{L} \times \mathbf{B}$
- Torque on current loop in uniform magnetic field:
- $\mu = IA$   $\tau = \mu \times B$
- Potential energy of magnetic dipole (current loop) in magnetic field

$$U = -\boldsymbol{\mu} \cdot \mathbf{B}$$

# The Source of the Magnetic Field: Moving Charges



### Biot-Savart law

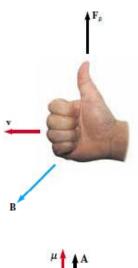
$$d\mathbf{B} = \frac{\mu_0}{4\pi} \frac{I \, d\mathbf{s} \times \hat{\mathbf{r}}}{r^2}$$

- The vector  $d\mathbf{B}$  is perpendicular both to  $d\mathbf{s}$  (which points in the direction of the current) and to the unit vector  $\hat{\mathbf{r}}$  directed from  $d\mathbf{s}$  toward P.
- The magnitude of dB is inversely proportional to r<sup>2</sup>, where r is the distance from ds to P.
- The magnitude of dB is proportional to the current and to the magnitude ds of the length element ds.
- The magnitude of  $d\mathbf{B}$  is proportional to  $\sin \theta$ , where  $\theta$  is the angle between the vectors  $d\mathbf{s}$  and  $\hat{\mathbf{r}}$ .

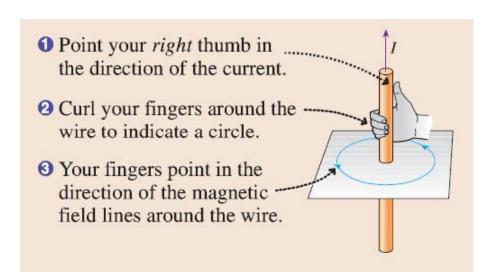
#### MIT Biot Savart visualization

http://ocw.mit.edu/ans7870/8/8.02T/f04/visualizations/magnet ostatics/03-CurrentElement3d/CurrentElement3d.htm

### **Summary of three Right Hand Rules:**







### **Applying the Biot-Savart Law**

Arbitrary shaped currents difficult to calculate

Simple cases, one can solve relatively easily with pen and paper: current loops, straight wire segments

Last time, we found B-field for straight wire segment with current in x- direction:

$$\overrightarrow{B} = \frac{M_0}{4\pi} \stackrel{\text{I}}{=} \left[ \frac{x_f}{X_f^2 + a^2} - \frac{x_i}{X_i^2 + a^2} \right] \stackrel{\text{A}}{=}$$

$$x_f$$

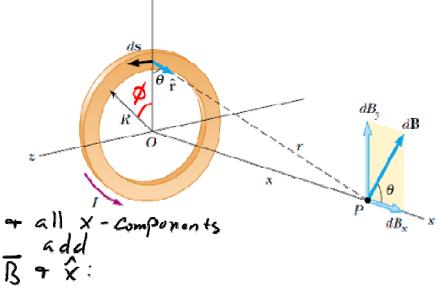
And limit xf=-xi=L-> infinity for an infinitely long straight wire:

#### **Applying the Biot-Savart Law: Circular arc** → **Circle**

http://ocw.mit.edu/ans7870/8/8.02T/f04/visualizations/magnetostatics/08-RingMagInt/MagRingIntFullScreen.htm

http://ocw.mit.edu/ans7870/8/8.02T/f04/visualizations/magnetost atics/09-RingMagField/RingMagFieldFullScreen.htm

### Applying the Biot-Savart Law: On-axis of circular loop



When we integrate,  $By \rightarrow 0 \rightarrow all \times - components$ Let O be angle between  $d\overline{B} \rightarrow \hat{x}$ :  $|d\overline{B}| = d\overline{B} \cdot \hat{x} = 1dB1 Cos O$ 

$$C_{R} O = \frac{R}{r}$$
,  $r = \sqrt{\chi^2 + R^2}$ ,  $d\vec{s} \perp \hat{r}$   
=>  $|d\vec{s}| = R d\emptyset$ 

$$|\vec{B}| = \int |dB| = \frac{M_0}{4\pi} I \int \frac{R d\phi}{r^2} \frac{R}{r}$$

$$\vec{B} = \frac{M_0}{2} I \frac{R^2}{(\chi^2 + R^2)^{3/2}} \hat{\chi}$$

# Applying the Biot-Savart Law: On-axis of circular loop

$$\vec{B} = \frac{\mu_0}{2} T \frac{R^2}{(\chi^2 + R^2)^{3/2}} \hat{\chi}$$

$$\lim_{\chi \to 0} \vec{B} = \frac{\mu_0 T}{2 R} \hat{\chi}$$

Jet 
$$\times >> R$$
,  $\Rightarrow (x^2 + R^2)^{3/2} = x^3 \left(1 + \frac{R^2}{x^2}\right)^{3/2}$   
 $\Rightarrow B = M_b a \frac{T \pi R^2 x}{x^3}$ 

$$\Rightarrow \vec{B} = \frac{\mu_0}{4\pi} \frac{2\pi}{x^3} \quad \text{on axis}$$

## Applying the Biot-Savart Law: On-axis of circular loop

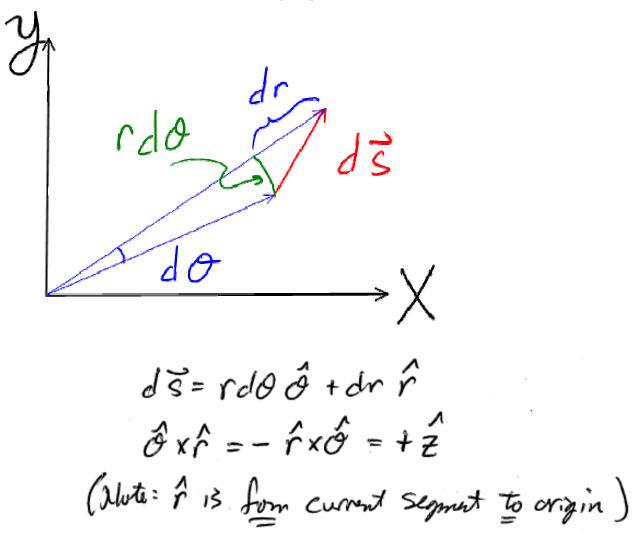
$$\Rightarrow \vec{B} = \frac{M_0}{4\pi} \quad \frac{2\pi}{x^3} \quad \text{on axis} \quad \frac{dB_0}{dB_x}$$

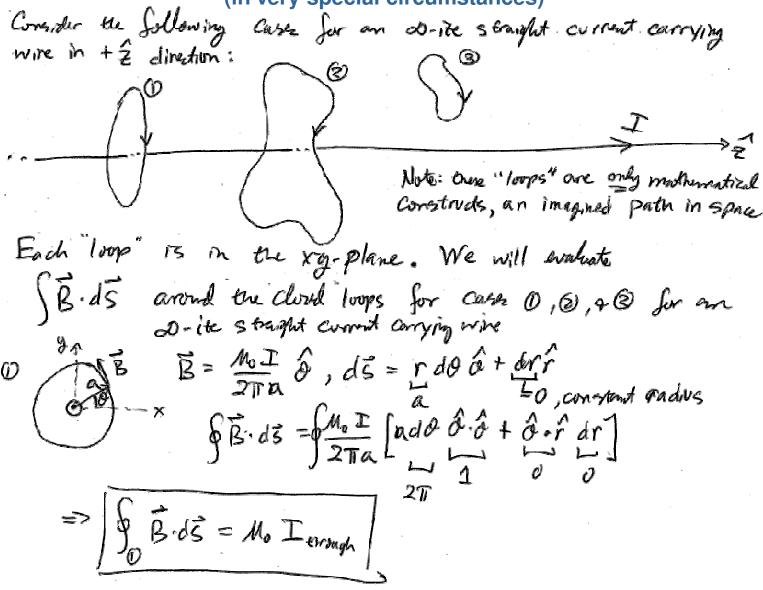
$$\overrightarrow{E} = \overrightarrow{4\pi} \mathcal{E}_{x} \xrightarrow{\overrightarrow{2P}}$$

Also Recall, 
$$\vec{\tau}_{g} = \vec{\Lambda} \times \vec{B}$$
  $\vec{\tau}_{e} = \vec{p} \times \vec{E}$ 

$$\vec{U}_{g} = -\vec{\mu} \cdot \vec{B}$$
  $\vec{U}_{e} = -\vec{p} \cdot \vec{E}$ 

Current Loops are "magnetic Dipoles"





For any arbitrary loop (not just 2-D loops!):

Ampere's Law 
$$S \vec{B} \cdot d\vec{s} = M_0 \vec{T}_{through}$$

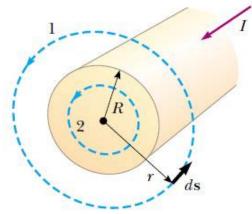
Use Ampere's Law to find B-field from current (in very special circumstances)

- Current that does not go through "Amperian Loop" does not contribute to the integral
- 2. Current through is the "net" current through loop
- 3. Try to choose loops where B-field is either parallel or perpendicular to ds, the Amperian loop. To do this, remember that symmetry is your friend!

Review pages 850-853!!

### Ampere's Law: Example, Finite size infinite wire

Calculate the B-field everywhere from a finite size, straight, infinite wire with uniform current.



From symmetry,
Br=0 (reverse current and flip cylinder)
Bz=0 (B=0 at infinity, Amperian rectangular loop
from infinity parallel to axial direction implies zero Bz
everywhere)

Only azimuthal component exists. Therefore, amperian loops are circles such that B parallel to ds.

#### Ampere's Law: Example, Finite size infinite wire

Calculate the B-field everywhere from a finite size, straight, infinite wire with uniform current.

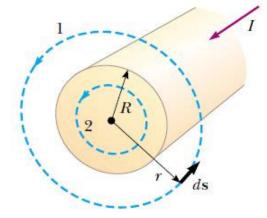
$$\frac{1}{r}$$

$$\frac{1}{ds}$$

direction from RHR

#### Ampere's Law: Example, Finite size infinite wire

Calculate the B-field everywhere from a finite size, straight, infinite wire with uniform current.



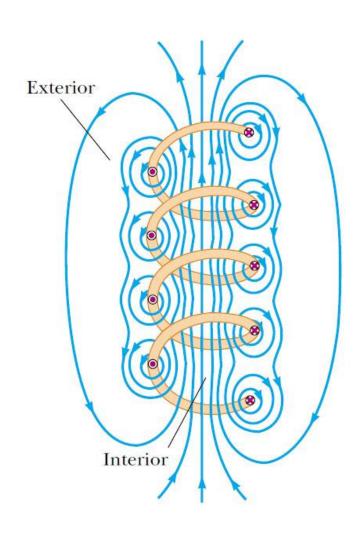
Case II: 
$$r \ge R$$
 inside wire

$$I_{enc} = \frac{\pi r^2}{\pi R^2} I$$

$$\oint \vec{B} \cdot d\vec{s} = \int_0^{2\pi} \vec{B} r d\theta = 2\pi r B = M_0 I_{enc}$$

$$\vec{B} = \frac{M_0 I}{2\pi} \frac{r}{R^2} \quad \text{direction from } RHR$$

#### Ampere's Law: Example, Infinitely long solenoid



As coils become more closely spaced, and the wires become thinner, and the length becomes much longer than the radius,

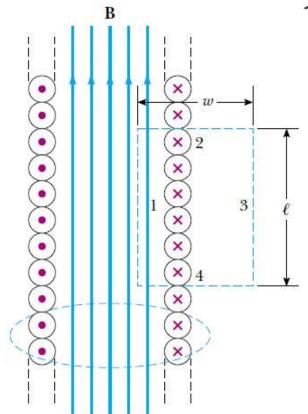
- 1. The B-field outside becomes very, very small (not at the ends, but away from sides)
- 2. The B-field inside points along the axial direction of the cylinder

Symmetry arguments for a sheet of current around a long cylinder:

- 1. Br=0 time reversal + flipping cylinder, but time reversal would flip Br!
- 2. Azimuthal component? No, since if we choose Amperian loop perpendicular to axis, no current pierces it.
- 3. B=0 everywhere outside: any Amperian loop outside has zero current through it

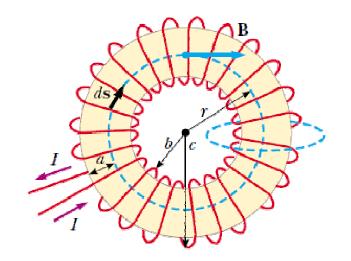
### Ampere's Law: Example, Infinitely long solenoid





13  $l = M_0(\frac{N}{L} lI) \Rightarrow B = M_0 MI, RHR$ Where m = # of turns per lengthB is Uniform inside Solenoid!!

### Ampere's Law: Example, Toroid

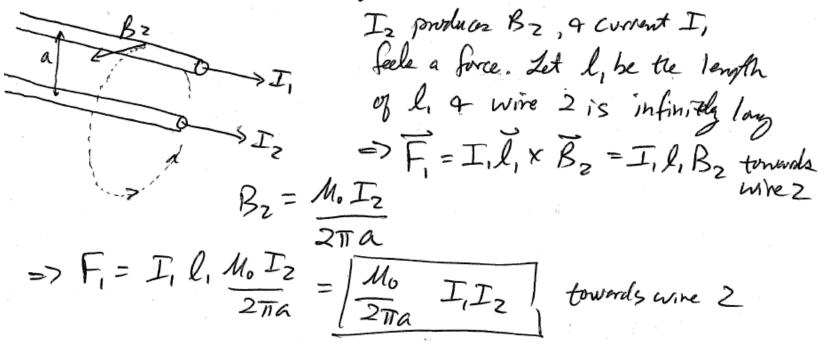


Solenoid bent in shape of donut. B is circumferential.

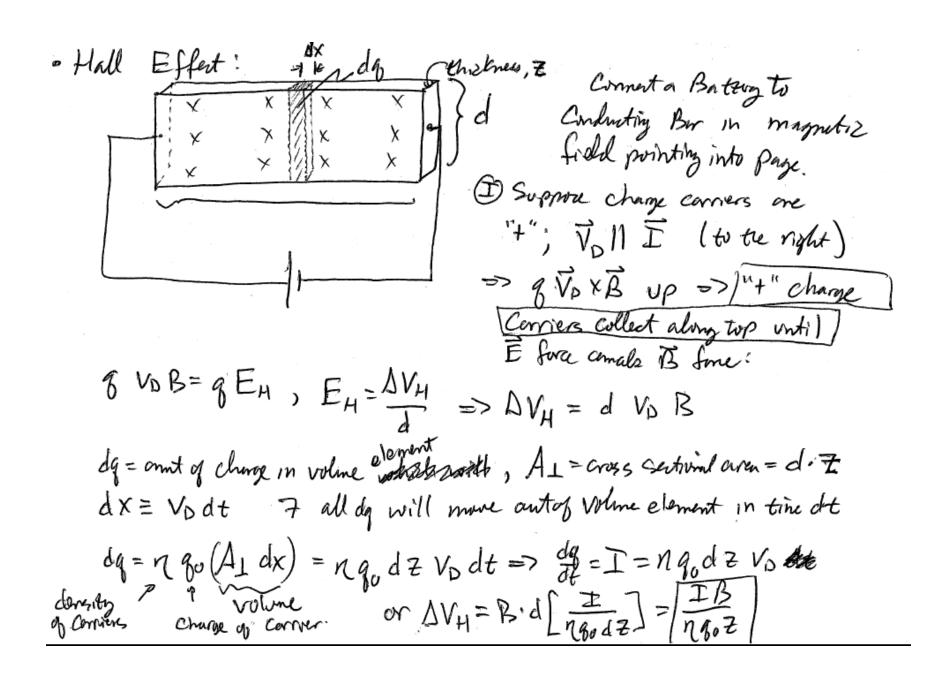
.. Draw amperim Loop as circle inside torus >> BII ds

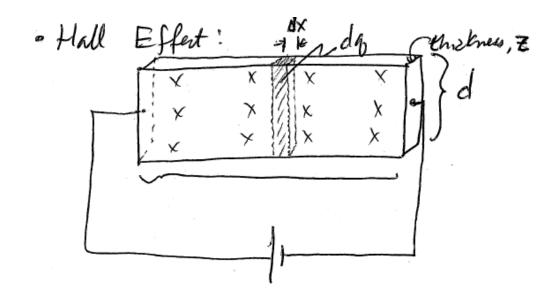
### Force Between two parallel, straight current carrying wires:

- one wire produces a B-field @ location of otherwise. Consider 2 parallel wires Carrying Corrent:



Parallel currents attract, Opposite currents repel.





Supprise change corners "-"; VDB in opposite direction of Cornect

(to left)

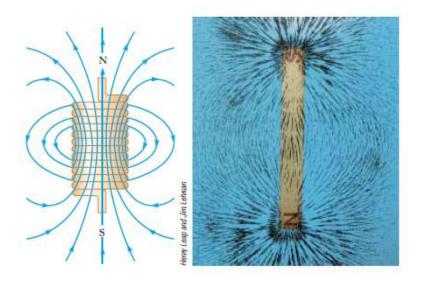
regardine down

change

in [11-" Changes will Brild up on top)

#### **Permanent magnets related to (tiny) currents:**

Current loops look like magnets, and vice versa:



Permanent magnets can be thought of as a many tiny current loops created by the 'spin' of the electron. These tiny current loops (magnetic moments) tend to line up creating a macroscopic, large magnetic field. Note that, at least from a classical point of view, a charged sphere spinning creates a circulating current → magnetic field.