

ENERGY CONSERVATION PRINCIPLE REVISITED: ELECTRIC POTENTIAL

Now that we have a new force

$$\underline{F_E} = \frac{k_e Q_1 Q_2}{r^2} \hat{r} \longrightarrow (1)$$

And a new field

$$\underline{E} = \frac{\underline{F_E}}{q} \longrightarrow (2)$$

We need to take another look at the Principle of Conservation of Energy.

First, let us recall some of our discussion from 121 where we talked only of mechanical energy:

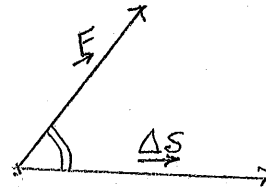
MECHANICAL WORK

$$\Delta W = \underline{F} \bullet \underline{\Delta S} = F \Delta S \cos(\underline{F}, \underline{\Delta S})$$

Where

\underline{F} = Force Vector

$\underline{\Delta S}$ = Displacement Vector



Note $\Delta W = 0$ if $\underline{F} \perp \underline{\Delta S}$, that is only component of $\underline{F} \parallel \underline{\Delta S}$ does work

KINETIC ENERGY

Work stored in motion: if an object of mass M is sitting at rest, the work required to give it a speed V is stored as Kinetic Energy

$$K = \frac{1}{2} M V^2$$

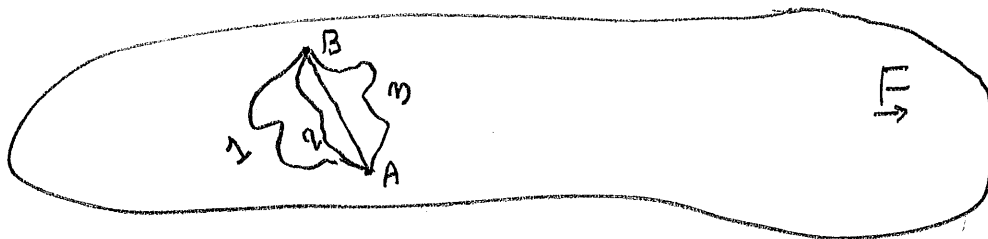
or since linear momentum $\underline{p} = M \underline{V}$ we can write $K = \frac{p^2}{2M}$

Potential Energy (U) Presents a greater conceptual challenge.

U is the mechanical work stored in a system when it is prepared (or put together) in the presence of a prevailing conservative force.

Supposed we have a region of space in which there is a prevailing force (weight near Earth's surface comes to mind). That is, at every point in this region an object will experience a force.

Let the object be at point B [First, notice that you can't let the object go as \underline{F} will immediately cause q and object will move].



To define U at B we have to calculate how much work was needed to put the object at B in the presence of \underline{F} . Let us pick some point A, where we can claim that U is known, and calculate the work needed to go from A to B. As soon as we try to do that we realize that the only way we can get a meaningful answer is if the work required to go from A to B is independent of the path taken. So our prevailing force has to be special. Such a force is called a CONSERVATIVE FORCE – WORK DONE DEPENDS ONLY ON END-POINTS AND NOT ON THE PATH TAKEN.

If that is true we have a unique answer

$$\Delta W_1 = \Delta W_2 = \Delta W_3 = \Delta W_{AB}$$

and we can use this fact to calculate change in U in going from A to B

$$\Delta U_{AB} = -\underline{F} \bullet \underline{\Delta S_{AB}}$$

NOTE THE NEGATIVE SIGN: it comes about because as stated above we cannot let the object go. In fact, the displacement from A to B must be carried out in such a way that the object cannot change its speed (if any). That is, we need to apply a force $-\underline{F}$ to balance the ambient \underline{F} at every point. The net force will become zero at all points. ΔU_{AB} is work being done by $-\underline{F}$.

So when \underline{F} is conservative ΔU_{AB} is unique. In the final step we can choose A such that $U_A = 0$. Then $U_B = -\underline{F} \bullet \underline{\Delta S_{AB}}$

Using the above definition we discussed two cases

- (i) U for Earth-Mass
System: Near earth
The Conservative Force is

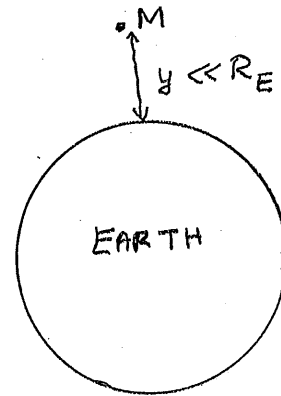
$$\underline{F}_g = -Mg\hat{y}$$

Hence

$$U_g(y) = +Mgy$$

Taking $U_g = 0$ for $y = 0$

(3)



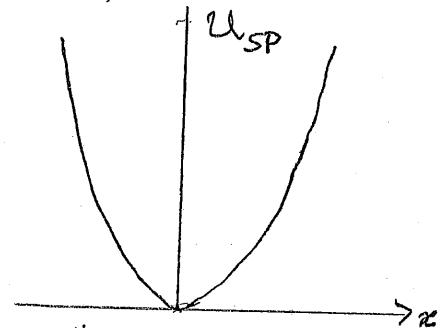
- (ii) U for Mass attached to a spring.
Here the conservative force is

$$\underline{F} = -kx\hat{x}$$

Hence

$$U_{sp}(x) = \frac{1}{2}kx^2$$

(4)



Taking $U = 0$, when $x = 0$ [spring relaxed]

We were then able to write the principle of Mechanical Energy Conservation

$$K_f + U_{gf} + U_{spf} = K_i + U_{gi} + U_{spi} + W_{NCF} \quad (5)$$

Where i and f refer to the initial and final state and W_{NCF} takes account of work done by non-conservative forces (friction for instance) in going from i to f .

When we got to thermodynamic systems we learnt that the system can change its energy in 3 ways.

Exchange heat \underline{DQ} with its surroundings because of a temperature difference across a conducting wall

Have mechanical work \underline{DW} done on or by it

Change the internal energy stored within it (dU)

The Conservation Law (First Law of Thermodynamics) Became

$$\pm DQ \pm DW \pm dU = 0$$

That is in any thermodynamic process the total change in energy must be ZERO

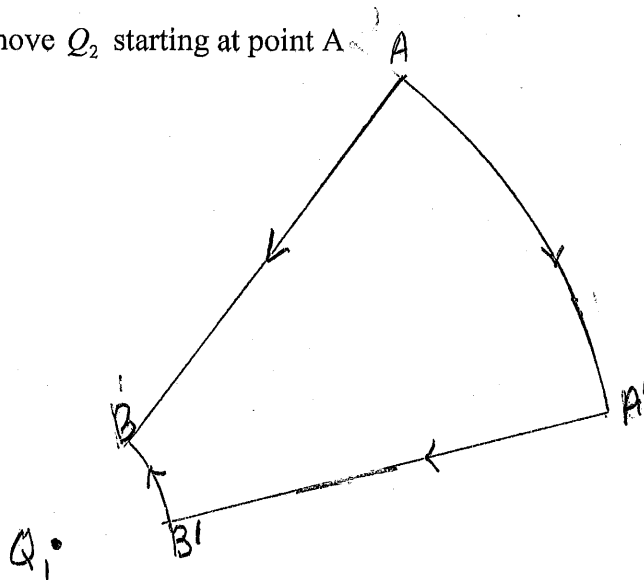
Now, let us look at $\underline{F_E}$ from equation (1). The first step is to examine if it is a conservative force. If so, we can define a potential energy for $\underline{F_E}$.

Note: in the following proof it is CRUCIAL to recognize that $\underline{F_E}$ acts only along the line joining the two charges and so work done by $\underline{F_E}$ being

$$\Delta W = \underline{F_E} \cdot \underline{\Delta S}$$

Will be ZERO for any displacement along the circumference (i.e. $\perp \hat{r}$)

Let us fix Q_1 and move Q_2 starting at point A



First Path

$\underline{\Delta S}$ is AB along \hat{r} work done will be

$$\Delta W_{AB} = \underline{F_E} \cdot \underline{\Delta S_{AB}}$$

Second Path

First, go from $A \rightarrow A'$ along circumference

$$\Delta W_{AA'} = 0$$

Next go along \hat{r} from A' to B' when $A'B' = AB$

$$\Delta W_{A'B'} = \underline{F_E} \cdot \underline{\Delta S_{A'B'}} = \Delta W_{AB}$$

Next go from B' to B along circumference

$$\Delta W_{B'B} = 0$$

Hence

$$\Delta W_{AA'B'B} = \Delta W_{AB}$$

Work is independent of path $\underline{F_E}$ is indeed conservative, potential energy is definable.

$$\Delta U_E = -\underline{F_E} \cdot \underline{\Delta S}$$

Note the minus sign. As always, the force which does the work must be equal and opposite to the conservative force. ΔU_E is the change in electrostatic potential energy consequent upon a displacement $\underline{\Delta S}$.

The Energy Conservation Equation will now read

$$K_f + U_{gf} + U_{spf} + U_{Ef} = K_i + U_{gi} + U_{spi} + U_{Ei} + W_{NCF} \quad (7)$$

Where again f and i , respectively refer to the final and initial states of the system, and W_{NCF} is work done by non-conservative forces while system goes from i to f .

In the present case it is useful to define a new quantity called Electrostatic Potential which is related to ΔU_E by the equation

$$\Delta V = \frac{\Delta U_E}{q} = \frac{-\underline{F_E} \cdot \underline{\Delta S}}{q}$$

$$\text{Potential} = -\underline{E} \cdot \underline{\Delta S}$$

ΔV = change of potential energy per unit charge

Like ΔU_E , ΔV is also a scalar, the dimensions are $ML^2T^{-2}Q^{-1}$ and the unit is Joule/coulomb which is called a Volt.