

CHAPTER 7

PROBLEM 7.1 (a) $\langle V \rangle = 2\alpha A^2 \int_0^{\infty} x e^{-2bx} dx = 2\alpha A^2 \left(-\frac{1}{4b} e^{-2bx} \right) \Big|_0^{\infty} = \frac{\alpha A^2}{2b} = \frac{\alpha}{2b} \sqrt{\frac{2b}{\pi}} = \frac{\alpha}{\sqrt{2b\pi}}$.

$\therefore \langle H \rangle = \frac{\hbar^2 b}{2m} + \frac{\alpha}{\sqrt{2b\pi}}$. $\frac{\partial \langle H \rangle}{\partial b} = \frac{\hbar^2}{2m} - \frac{1}{2} \frac{\alpha}{\sqrt{2\pi}} b^{-3/2} = 0 \Rightarrow b^{3/2} = \frac{\alpha}{\sqrt{2\pi}} \frac{m}{\hbar^2}$; $b = \left(\frac{m\alpha}{\sqrt{2\pi}\hbar^2} \right)^{2/3}$.

$\langle H \rangle_{\min} = \frac{\hbar^2}{2m} \left(\frac{m\alpha}{\sqrt{2\pi}\hbar^2} \right)^{2/3} + \frac{\alpha}{\sqrt{2\pi}} \left(\frac{\sqrt{2\pi}\hbar^2}{m\alpha} \right)^{1/3} = \frac{\alpha^{2/3} \hbar^{2/3}}{m^{1/3} (2\pi)^{1/3}} \left(\frac{1}{2} + 1 \right) = \boxed{\frac{3}{2} \left(\frac{\alpha^2 \hbar^2}{2\pi m} \right)^{1/3}}$.

(b) $\langle V \rangle = 2\alpha A^2 \int_0^{\infty} x^4 e^{-2bx} dx = 2\alpha A^2 \frac{3}{8(2b)^4} \sqrt{\frac{\pi}{2b}} = \frac{3\alpha}{16b} \sqrt{\frac{\pi}{2b}} \sqrt{\frac{2b}{\pi}} = \frac{3\alpha}{16b}$.

$\therefore \langle H \rangle = \frac{\hbar^2 b}{2m} + \frac{3\alpha}{16b}$. $\frac{\partial \langle H \rangle}{\partial b} = \frac{\hbar^2}{2m} - \frac{3\alpha}{8b^2} = 0 \Rightarrow b^3 = \frac{3\alpha m}{4\hbar^2}$; $b = \left(\frac{3\alpha m}{4\hbar^2} \right)^{1/3}$.

$\langle H \rangle_{\min} = \frac{\hbar^2}{2m} \left(\frac{3\alpha m}{4\hbar^2} \right)^{1/3} + \frac{3\alpha}{16} \left(\frac{4\hbar^2}{3\alpha m} \right)^{2/3} = \frac{\alpha^{1/3} \hbar^{4/3}}{m^{2/3}} 3^{1/3} 4^{-1/3} \left(\frac{1}{2} + \frac{1}{4} \right) = \boxed{\frac{3}{4} \left(\frac{3\alpha \hbar^4}{4m^2} \right)^{1/3}}$.

PROBLEM 7.2 Normalize: $1 = 2|A|^2 \int_0^{\infty} \frac{1}{(x^2+b^2)^2} dx = 2|A|^2 \frac{\pi}{4b^3} = \frac{\pi}{2b^3} |A|^2$. $A = \sqrt{\frac{2b^3}{\pi}}$.

Kinetic energy: $\langle T \rangle = -\frac{\hbar^2}{2m} |A|^2 \int_0^{\infty} \frac{1}{(x^2+b^2)^2} \frac{d^2}{dx^2} \left(\frac{1}{(x^2+b^2)} \right) dx$

$\frac{d}{dx} \left(\frac{-2x}{(x^2+b^2)^2} \right) = \frac{-2}{(x^2+b^2)^2} + 2x \frac{4x}{(x^2+b^2)^3} = \frac{2(3x^2-b^2)}{(x^2+b^2)^3}$

$\langle T \rangle = -\frac{\hbar^2}{2m} \cdot \frac{2b^3}{\pi} \cdot 4 \int_0^{\infty} \frac{(3x^2-b^2)}{(x^2+b^2)^4} dx = -\frac{4\hbar^2 b^3}{\pi m} \left\{ 3 \int_0^{\infty} \frac{1}{(x^2+b^2)^3} dx - 4b^2 \int_0^{\infty} \frac{1}{(x^2+b^2)^4} dx \right\}$

$= -\frac{4\hbar^2 b^3}{\pi m} \left\{ 3 \cdot \frac{3\pi}{16b^3} - 4b^2 \cdot \frac{5\pi}{32b^3} \right\} = \frac{\hbar^2}{4mb^2}$.

Potential energy: $\langle V \rangle = \frac{1}{2} m\omega^2 |A|^2 2 \int_0^{\infty} \frac{x^2}{(x^2+b^2)^2} dx = m\omega^2 \frac{2b^3}{\pi} \cdot \frac{\pi}{4b} = \frac{1}{2} m\omega^2 b^2$.

$\therefore \langle H \rangle = \frac{\hbar^2}{4mb^2} + \frac{1}{2} m\omega^2 b^2$. $\frac{\partial \langle H \rangle}{\partial b} = -\frac{\hbar^2}{2mb^3} + m\omega^2 b = 0 \Rightarrow b^4 = \frac{\hbar^2}{2m^2\omega^2} \Rightarrow b^2 = \frac{1}{\sqrt{2}} \frac{\hbar}{m\omega}$.

$\therefore \langle H \rangle_{\min} = \frac{\hbar^2}{4m} \frac{\sqrt{2} m\omega}{\hbar} + \frac{1}{2} m\omega^2 \frac{1}{\sqrt{2}} \frac{\hbar}{m\omega} = \hbar\omega \left(\frac{\sqrt{2}}{4} + \frac{1}{2\sqrt{2}} \right) = \boxed{\frac{\sqrt{2}}{2} \hbar\omega} = 0.707\hbar\omega > \frac{1}{2} \hbar\omega$. ✓

Problem 7.4 (a) Follow the proof in § 7.1: $\psi = \sum_{n=1}^{\infty} C_n \psi_n$, where ψ_1 is the ground state. Since $\langle \psi_1 | \psi \rangle = 0$,

we have: $\sum_{n=1}^{\infty} C_n \langle \psi_1 | \psi_n \rangle = C_1 = 0$ — the coefficient of the ground state is zero. So

$$\langle H \rangle = \sum_{n=2}^{\infty} E_n |C_n|^2 \geq E_f \sum_{n=2}^{\infty} |C_n|^2 = E_f, \text{ since } E_n \geq E_f \text{ for all } n \text{ except } 1.$$

$$(b) 1 = |A|^2 \int_{-\infty}^{\infty} x^2 e^{-2bx^2} dx = |A|^2 \cdot \frac{1}{8b} \sqrt{\frac{\pi}{2b}} \Rightarrow |A|^2 = 4b \sqrt{\frac{2b}{\pi}}.$$

$$\langle T \rangle = -\frac{\hbar^2}{2m} |A|^2 \int_{-\infty}^{\infty} x e^{-bx^2} \frac{d}{dx} (x e^{-bx^2}) dx$$

$$\frac{d}{dx} (x e^{-bx^2} - 2bx^2 e^{-bx^2}) = -2bx e^{-bx^2} - 4bx e^{-bx^2} + 4b^2 x^3 e^{-bx^2}$$

$$\langle T \rangle = -\frac{\hbar^2}{2m} 4b \sqrt{\frac{2b}{\pi}} \int_{-\infty}^{\infty} (-6bx^2 + 4b^2 x^4) e^{-2bx^2} dx = -\frac{2\hbar^2 b}{m} \sqrt{\frac{2b}{\pi}} \left[-6b \frac{1}{8b} \sqrt{\frac{\pi}{2b}} + 4b^2 \frac{3}{32b^2} \sqrt{\frac{\pi}{2b}} \right]$$

$$= -\frac{4\hbar^4 b}{m} \left(-\frac{3}{4} + \frac{3}{8} \right) = \frac{3\hbar^4 b}{2m}.$$

$$\langle V \rangle = \frac{1}{2} m \omega^2 |A|^2 \int_{-\infty}^{\infty} x^2 e^{-2bx^2} x^2 dx = \frac{1}{2} m \omega^2 4b \sqrt{\frac{2b}{\pi}} \cdot \frac{3}{32b^2} \sqrt{\frac{\pi}{2b}} = \frac{3m\omega^2}{8b}.$$

$$\langle H \rangle = \frac{3\hbar^4 b}{2m} + \frac{3m\omega^2}{8b}; \quad \frac{\partial \langle H \rangle}{\partial b} = \frac{3\hbar^4}{2m} - \frac{3m\omega^2}{8b^2} = 0 \Rightarrow b^2 = \frac{m^2 \omega^2}{4\hbar^2} \Rightarrow b = \frac{m\omega}{2\hbar}.$$

$$\therefore \langle H \rangle_{\min} = \frac{3\hbar^4}{2m} \frac{m\omega}{2\hbar} + \frac{3m\omega^2}{8} \frac{2\hbar}{m\omega} = \hbar\omega \left(\frac{3}{4} + \frac{3}{4} \right) = \boxed{\frac{3}{2} \hbar\omega}. \text{ (Which is exact, since the trial wave}$$

function is in the form of the true first excited state.)

Problem 7.5 (a) Use the unperturbed ground state (ψ_0^0) as the trial wave function. The variational principle says $\langle \psi_0^0 | H | \psi_0^0 \rangle \geq E_0$. But $H = H^0 + H^1$, so $\langle \psi_0^0 | H | \psi_0^0 \rangle = \langle \psi_0^0 | H^0 | \psi_0^0 \rangle + \langle \psi_0^0 | H^1 | \psi_0^0 \rangle$.

But $\langle \psi_0^0 | H^0 | \psi_0^0 \rangle = E_0^0$ (the unperturbed ground state energy), and $\langle \psi_0^0 | H^1 | \psi_0^0 \rangle$ is precisely the first order correction to the ground state energy [6.9], so

$$E_0^0 + E_0^1 \geq E_0. \quad \text{Q.E.D.}$$

(b) The second-order correction (E_0^2) is $E_0^2 = \sum_{m \neq 0} \frac{|\langle \psi_m^0 | H^1 | \psi_0^0 \rangle|^2}{E_0^0 - E_m^0}$. But the numerator is

clearly positive, and the denominator is always negative (since $E_0^0 < E_m^0$ for all m), so E_0^2 is negative.

PROBLEM 10.10 (a) Check the answer given: $x_c = \omega \int_0^t f(t') \sin[\omega(t-t')] dt' \Rightarrow x_c(0) = 0 \checkmark$

$$\dot{x}_c = \omega f(t) \sin[\omega(t-t)] + \omega^2 \int_0^t f(t') \cos[\omega(t-t')] dt' = \omega^2 \int_0^t f(t') \cos[\omega(t-t')] dt' \Rightarrow \dot{x}_c(0) = 0 \checkmark$$

$$\ddot{x}_c = \omega^2 f(t) \cos[\omega(t-t)] - \omega^2 \int_0^t f(t') \sin[\omega(t-t')] dt' = \omega^2 f(t) - \omega^2 x_c.$$

Now, the classical equation of motion is: $m \frac{d^2 x}{dt^2} = -m\omega^2 x + m\omega^2 f$. For the proposed solution

$m \frac{d^2 x_c}{dt^2} = m\omega^2 f - m\omega^2 x_c$, so it does satisfy the equation of motion, with appropriate boundary conditions.

(b) Let $z \equiv x - x_c$ (so $\psi_n(x - x_c) = \psi_n(z)$, and z depends on t as well as x).

$$\frac{\partial \Psi}{\partial t} = \frac{d\psi_n}{dz} (-\dot{x}_c) e^{i\{z\}} + \psi_n e^{i\{z\}} \left[\frac{i}{\hbar} \left[-(n+\frac{1}{2})\hbar\omega + m\ddot{x}_c(x - \frac{x_c}{\omega}) - \frac{m}{2}\dot{x}_c^2 + \frac{m\omega^2}{2} f x_c \right] \right]$$

$$[\] = -(n+\frac{1}{2})\hbar\omega + \frac{m\omega^2}{2} (2x(f - x_c) + x_c^2 - \dot{x}_c^2/\omega^2).$$

$$\therefore \frac{\partial \Psi}{\partial t} = -\dot{x}_c \frac{d\psi_n}{dz} e^{i\{z\}} + i \Psi \left[-(n+\frac{1}{2})\omega + \frac{m\omega^2}{2\hbar} (2x(f - x_c) + x_c^2 - \frac{1}{\omega^2} \dot{x}_c^2) \right].$$

$$\frac{\partial \Psi}{\partial x} = \frac{d\psi_n}{dz} e^{i\{z\}} + \psi_n e^{i\{z\}} \frac{i}{\hbar} [m\dot{x}_c]; \quad \frac{\partial^2 \Psi}{\partial x^2} = \frac{d^2 \psi_n}{dz^2} e^{i\{z\}} + 2 \frac{d\psi_n}{dz} e^{i\{z\}} \frac{i}{\hbar} (m\dot{x}_c) - \left(\frac{m\dot{x}_c}{\hbar}\right)^2 \psi_n e^{i\{z\}}$$

$$\therefore H\Psi = -\frac{\hbar^2}{2m} \frac{\partial^2 \Psi}{\partial x^2} + \frac{1}{2} m\omega^2 x^2 \Psi - m\omega^2 f x \Psi = -\frac{\hbar^2}{2m} \frac{d^2 \psi_n}{dz^2} e^{i\{z\}} - \frac{\hbar^2}{2m} 2 \frac{d\psi_n}{dz} e^{i\{z\}} \frac{i m \dot{x}_c}{\hbar} + \frac{\hbar^2}{2m} \left(\frac{m\dot{x}_c}{\hbar}\right)^2 \Psi + \frac{1}{2} m\omega^2 x^2 \Psi$$

$$- m\omega^2 f x \Psi. \quad \text{But } -\frac{\hbar^2}{2m} \frac{d^2 \psi_n}{dz^2} + \frac{1}{2} m\omega^2 z^2 \psi_n = (n+\frac{1}{2})\hbar\omega \psi_n, \text{ so}$$

$$H\Psi = (n+\frac{1}{2})\hbar\omega \Psi - \frac{1}{2} m\omega^2 z^2 \Psi - i\hbar \dot{x}_c \frac{d\psi_n}{dz} e^{i\{z\}} + \frac{m}{2} \dot{x}_c^2 \Psi + \frac{1}{2} m\omega^2 x^2 \Psi - m\omega^2 f x \Psi$$

$$\stackrel{?}{=} i\hbar \frac{\partial \Psi}{\partial t} = -i\hbar \dot{x}_c \frac{d\psi_n}{dz} e^{i\{z\}} - \hbar \Psi \left[-(n+\frac{1}{2})\omega + \frac{m\omega^2}{2\hbar} (2xf - 2xx_c + x_c^2 - \frac{1}{\omega^2} \dot{x}_c^2) \right]$$

$$-\frac{1}{2} m\omega^2 z^2 + \frac{m}{2} x_c^2 + \frac{1}{2} m\omega^2 x^2 - m\omega^2 f x \stackrel{?}{=} -\frac{m\omega^2}{2} (2xf - 2xx_c + x_c^2 - \frac{1}{\omega^2} \dot{x}_c^2)$$

$$z^2 - x_c^2 \stackrel{?}{=} -2xx_c + x_c^2; \quad z^2 \stackrel{?}{=} (x^2 - 2xx_c + x_c^2) = (x - x_c)^2 \quad \checkmark$$

$$(c) [10.99] \Rightarrow H = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + \frac{1}{2} m\omega^2 (x^2 - 2xf + f^2) - \frac{1}{2} m\omega^2 f^2. \quad \text{Shift origin: } u \equiv x - f.$$

$$H = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial u^2} + \frac{1}{2} m\omega^2 u^2 - \frac{1}{2} m\omega^2 f^2. \quad \text{So eigenfunctions are } \psi_n(u) = \psi_n(x-f), \text{ and}$$

eigenvalues are harmonic oscillator ones $(n+\frac{1}{2})\hbar\omega$, less the added constant: $E_n = (n+\frac{1}{2})\hbar\omega - \frac{1}{2} m\omega^2 f^2$.

(d) Note that $\sin[\omega(t-t')] = \frac{1}{\omega} \frac{d}{dt'} \cos[\omega(t-t')]$, so $x_c(t) = \int_0^t f(t') \frac{d}{dt'} \cos[\omega(t-t')] dt'$, or

$$x_c(t) = f(t) \cos[\omega(t-t)] \Big|_0^t - \int_0^t \left(\frac{df}{dt'}\right) \cos[\omega(t-t')] dt' = f(t) - \int_0^t \left(\frac{df}{dt'}\right) \cos[\omega(t-t')] dt' \quad (\text{since } f(0)=0).$$

Now, for adiabatic process we want df/dt very small - specifically, $\frac{df}{dt} \ll \omega f(t)$ ($0 < t \leq t$).

Then the integral is negligible compared to $f(t)$, and we have $x_c(t) \cong f(t)$. (Physically, this says that if you pull on the spring very gently, no fancy oscillations will occur - the mass just moves along as though attached to a string of fixed length.)

(e) Put $x_c \cong f$ into [10.101], using [10.102]:

$$\Psi(x,t) = \psi_n(x,t) e^{\frac{i}{\hbar} [-(n+\frac{1}{2})\hbar\omega t + m\dot{f}(x-f/2) + \frac{m\omega^2}{2} \int_0^t f^2(t') dt']}$$

The dynamic phase [10.41] is $\theta_n(t) = -\frac{1}{\hbar} \int_0^t E_n(t') dt' = -(n+\frac{1}{2})\hbar\omega t + \frac{m\omega^2}{2\hbar} \int_0^t f^2(t') dt'$, so

$\Psi(x,t) = \psi_n(x,t) e^{i\theta_n(t)} e^{i\gamma_n(t)}$, confirming [10.103], with the geometric phase given (obviously) by

$$\gamma_n(t) = \frac{m}{\hbar} \dot{f}(x-f/2).$$

But the eigen-functions here are real, and hence (see p. 338) the geometric phase should be zero.

The point is that (in the adiabatic approximation) \dot{f} is extremely small (see above), and hence in

this limit $\frac{m}{\hbar} \dot{f}(x-f/2) \cong 0$ (at least, in the only region of x where $\psi_n(x,t)$ is non-zero).