

Lecture 34 Transformation of Bases

①

For the Ammonia Molecule problem, we worked in the up & down basis. In this basis,

$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ means N-atom-up & $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ means N-atom-down.

The stationary states in this basis are

$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \sim$ energy eigenstate I in up & down basis $E_I = E_0 - A$

$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix} \sim$ energy eigenstate II in up & down basis $E_{II} = E_0 + A$.

The elements of these column vectors are QM amplitudes to observe N-atom-up & N-atom-down.

$\begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$ QM amplitude for N-atom-up
 QM amplitude for N-atom-down

~~We don't have to work in the up & down basis.~~

We can also work in the energy basis; where

$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ means energy eigenstate I & $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ means energy eigenstate II in the energy basis.

We found that up & down in terms of I & II are

$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$ means N-atom-up in the energy basis

$\begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$ means N-atom-down in the energy basis

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The elements of the column vectors in the energy basis are QM amplitudes

$$\begin{pmatrix} c_{I\sigma} \\ c_{II\sigma} \end{pmatrix} \begin{array}{l} \text{QM amplitude for energy } E_I \\ \text{QM amplitude for energy } E_{II} \\ \text{in the energy basis} \end{array}$$

we see that the meaning of the column vectors depends on the basis that we use.

Similarly, the operator matrix looks different in different basis. For example

$$\hat{H} = \begin{pmatrix} E_0 & -A \\ -A & E_0 \end{pmatrix} \text{ in the up \& down basis}$$

$$\hat{H} = \begin{pmatrix} E_I & 0 \\ 0 & E_{II} \end{pmatrix} \text{ in the energy basis}$$

$$= \begin{pmatrix} E_0 - A & 0 \\ 0 & E_0 + A \end{pmatrix}$$

In general we need to be able to convert our state vectors & operators from one basis to another. How can we transform a state vector or operator matrix from one basis to another?

For a state vector, we can always expand it in another basis like this:

Let i, j label the states in basis A
Let m, n label the state in basis B

An arbitrary state in basis A is written

$$|\psi\rangle = \left(\sum_i |i\rangle \langle i| \right) |\psi\rangle = \sum_i |i\rangle \underbrace{\langle i|\psi\rangle}_{\text{call this } a_i} = \sum_i a_i |i\rangle$$

The $\{a_i\}$ are the column vector elements in basis A. Similarly, in basis B the arbitrary state is

$$|\psi\rangle = \sum_m b_m |m\rangle, \quad \{b_m\} \text{ are the column vector elements in basis B.}$$

Suppose we know the $\{a_i\}$, and we want to calculate the $\{b_m\}$. How can we do this?

Like this

$$\begin{aligned} b_m &= \langle m|\psi\rangle = \langle m|\left(\sum_i |i\rangle \langle i|\right)|\psi\rangle \\ &= \sum_i \langle m|i\rangle \underbrace{\langle i|\psi\rangle}_{a_i} \end{aligned}$$

$$b_m = \sum_i a_i \langle m|i\rangle = \sum_i a_i U_{mi}, \quad \text{where } U_{mi} \equiv \langle m|i\rangle$$

This is a matrix equation. It says to transform from the A basis to the B basis we must know the overlap of ^{all} the basis vectors in both bases.

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In Matrix Notation

$$\begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ \vdots \end{pmatrix} = \begin{pmatrix} \langle 11| \rangle & \langle 12| \rangle & \langle 13| \rangle & \dots & a_1 \\ \langle 21| \rangle & \langle 22| \rangle & \langle 23| \rangle & \dots & a_2 \\ \langle 31| \rangle & \langle 32| \rangle & \langle 33| \rangle & \dots & a_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \ddots & \vdots \end{pmatrix}$$

or $|\psi_m\rangle = \hat{U} |\psi_i\rangle$
in Dirac Notation

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In this matrix, the bra-vectors are states in Basis B, and the ket-vectors are state in basis A. Unitary

The $\langle i|j\rangle$ matrix transforms the state vector from Basis A to Basis B.

Similarly, we can transform an operator matrix from A to B. Let \hat{F} be some operator whose matrix elements F_{ij} are known in basis A:

$$\hat{F} = \begin{pmatrix} F_{11} & F_{12} & F_{13} & \dots \\ F_{21} & F_{22} & F_{23} & \dots \\ F_{31} & F_{32} & F_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix} \quad F_{ij} = \langle i|\hat{F}|j\rangle$$

How can we calculate F_{mn} , the matrix elements in Basis B?

Answer:

$$\begin{aligned}
 F_{mn} &= \langle m | \hat{F} | n \rangle = \langle m | \left(\sum_i |i\rangle \langle i| \right) \hat{F} \left(\sum_j |j\rangle \langle j| \right) | n \rangle \\
 &= \sum_{ij} \langle m | i \rangle \langle i | \hat{F} | j \rangle \langle j | n \rangle \\
 &= \sum_{ij} \langle m | i \rangle F_{ij} \langle j | n \rangle
 \end{aligned}$$

$$F_{mn} = \sum_{ij} U_{mi} F_{ij} U_{nj}^* \quad \text{or } \hat{F}' = \hat{U} \hat{F} \hat{U}^{-1}$$

~~This is a Matrix Equation it says~~

$$\begin{pmatrix} F_{11} & F_{12} & F_{13} & \dots \\ F_{21} & F_{22} & F_{23} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix} = \begin{pmatrix} U_{11} & U_{12} & U_{13} \\ U_{21} & U_{22} & U_{23} \\ U_{31} & & \end{pmatrix}$$

~~U_{ij}~~

The matrix U_{mi} is related to U_{im} because

$$U_{mi} = \langle m | i \rangle = (\langle i | m \rangle)^* = U_{im}^*$$

The \hat{U} matrix is a "unitary" matrix, which means that it preserves the normalization of state vectors which it transforms. Mathematically, for a Unitary Matrix the inverse matrix \hat{U}^{-1} is the Hermitian Adjoint:

$$\hat{U}^\dagger = \hat{U}^{-1} \quad \text{for a unitary matrix}$$

Therefore $\hat{U} \hat{U}^{-1} = \mathbb{1} \leftarrow \text{identity matrix}$ $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

$\hat{U} \hat{U}^\dagger = \mathbb{1} \leftarrow$

We call the transformation defined by U a "Unitary-Similarity transformation". State vectors transform as

$$|\psi'\rangle = \hat{U} |\psi\rangle$$

Operators transform as

$$\hat{A}' = \hat{U} \hat{A} \hat{U}^{-1}$$

This is how we transform from one basis to another.

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Recap of Transformation of Basis in Matrix Mechanics.

Let i, j label states in basis A

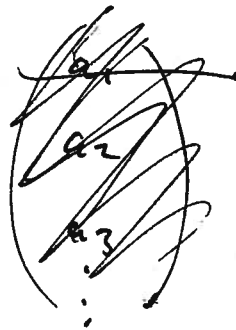
Let m, n label states in basis B

To transform a ~~state~~ column vector $\{a_i\}$ from basis A to a column vector $\{b_m\}$ in basis B do this

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$$b_m = \sum_i a_i U_{mi} \quad \text{where}$$

or same thing



$U_{mi} \equiv \langle m|i \rangle$
= overlap of
the basis B states
with the basis A states.

$$\begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} \langle 1|1 \rangle & \langle 1|2 \rangle & \langle 1|3 \rangle \\ \langle 2|1 \rangle & \langle 2|2 \rangle & \langle 2|3 \rangle \\ \langle 3|1 \rangle & \langle 3|2 \rangle & \langle 3|3 \rangle \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$

or same thing

$$|\psi_m\rangle = \hat{U} |\psi_i\rangle$$

To transform a Matrix written in basis A ($F_{ij} \equiv \langle i|\hat{F}|j \rangle$) to basis B ($F_{mn} \equiv \langle m|\hat{F}|n \rangle$) do this.

~~$$F_{mn} = \sum_{ij} U_{mi} F_{ij} U_{jn}$$~~

$$F_{mn} = \sum_{ij} \underbrace{\langle m|i \rangle}_{U_{mi}} \underbrace{\langle i|\hat{F}|j \rangle}_{F_{ij}} \underbrace{\langle j|n \rangle}_{V_{jn}} \quad \text{using Identity operator twice}$$

Since $V_{jn} = \langle j|n \rangle = (\langle n|j \rangle)^* = U_{nj}^*$
we can write

$$F_{mn} = \sum_{ij} U_{mi} F_{ij} U_{nj}^*$$

The U matrix has the following property which we will prove a little later:

$$U_{nj}^* = (U^{-1})_{jn}$$

← inverse matrix
note that these are reversed

∴ $F_{mn} = \sum_{ij} U_{mi} F_{ij} (U^{-1})_{jn}$ This is ~~A~~ Matrix

Multiplication done twice

In Matrix Notation $F_{\text{basis B}} = U F_{\text{basis A}} U^{-1}$

So we use the Matrix U and its inverse to convert the operator F from basis A to basis B.

Matrix Properties & the names we give them

Definition of Matrix Multiplication: AB in matrix notation

or $(AB)_{mn} = \sum_p A_{mp} B_{pn}$ in summation or matrix element notation

Definition of Inverse Matrix

A^{-1} is defined such that $A^{-1}A = I$ ← identity matrix.

In Matrix Element Notation:

$$\sum_p (A^{-1})_{mp} A_{pn} = I_{mn} = \delta_{mn}$$

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Definition of Transpose

$$(\tilde{A})_{mn} = A_{nm} \quad \text{"reverse the rows \& columns"}$$

↕
reversed

Definition of Hermitian Adjoint

From our wave mechanics definitions

Reverse this bracket by taking the complex conjugate

$$\langle \hat{A}^+ \alpha | \beta \rangle \equiv \langle \alpha | \hat{A} \beta \rangle \quad \text{definition of } \hat{A}^+$$

↓
 $A_{\alpha\beta}$ in matrix element notation

$$\langle \beta | \hat{A}^+ \alpha \rangle^*$$

↓
 $(A^+)_{\beta\alpha}^*$
↑
in matrix element notation

$$\therefore (A^+)_{\beta\alpha}^* \equiv A_{\alpha\beta}$$

↕
reversed

Definition of A^+ in Matrix Element notation.

Definition of a "Hermitian Matrix"

IF $A^+ = A$ we say "A is Hermitian"

Since $(A^+)_{\beta\alpha}^* \equiv A_{\alpha\beta}$ (Definition of A^+)

For a "Hermitian Matrix", $A^+ = A$, so we have

$$(A)_{\beta\alpha}^* = A_{\alpha\beta} \quad \text{for a Hermitian Matrix}$$

A Matrix is Hermitian if reversing rows & columns and taking the complex conjugate gives the same matrix. Example:

$$\begin{pmatrix} 1 & 3+i \\ 3-i & 5 \end{pmatrix}$$

is Hermitian

$$\begin{pmatrix} 1 & 3 \\ 3 & i \end{pmatrix}$$

is not Hermitian

violates Hermiticity

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Definition of a Unitary Matrix

If $A^+ = A^{-1}$, we say "A is Unitary"

In ~~the~~ matrix element notation,

if $(A^+)_{nm} = (A^{-1})_{mn}$ we say "A is Unitary"

↓

if $A_{nm}^* = (A^{-1})_{mn}$ we say "A is Unitary"

if ~~A_{nm}^*~~ $A_{nm}^* = (A^+)_{mn}$ we say "A is Unitary"

For a Unitary Matrix $AA^+ = I$ because $A^+ = A^{-1}$

In Matrix Element notation,

$$(AA^+)_{mn} = \delta_{mn}$$

or $\sum_p A_{mp} (A^+)_{pn} = \delta_{mn}$

or $\sum_p A_{mp} A_{np}^* = \delta_{mn}$ For a unitary Matrix A

Does Uni have this property? Let's check:

$$\sum_i U_{mi} U_{ni}^* \stackrel{?}{=} \delta_{mn} \quad \text{Is this true?}$$

$$\sum_i \langle m|i \rangle (\langle n|i \rangle)^* \stackrel{?}{=} \delta_{mn}$$

$$\sum_i \langle m|i \rangle \langle i|n \rangle \stackrel{?}{=} \delta_{mn}$$

$$\langle m | \left(\sum_i |i\rangle \langle i| \right) |n \rangle \stackrel{?}{=} \delta_{mn}$$

$\langle m|n \rangle \stackrel{?}{=} \delta_{mn}$ \leftarrow Yes, because the states of Basis B are orthonormal.

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Some simple QM systems in 1D position space

Schrodinger Eq in position space: $\psi''(x) = -\frac{2m}{\hbar^2} (E - V(x))$

Classically Allowed Region (CAR): $E - V(x) > 0$

$\Rightarrow \psi(x)$ oscillates with spatial ~~wavelength~~ ^{wavelength} ~~wavenumber~~ ^{wavenumber}

Classically Forbidden Region (CFR): $E - V(x) < 0$

$\Rightarrow \psi(x)$ decays

Other conditions for ψ :

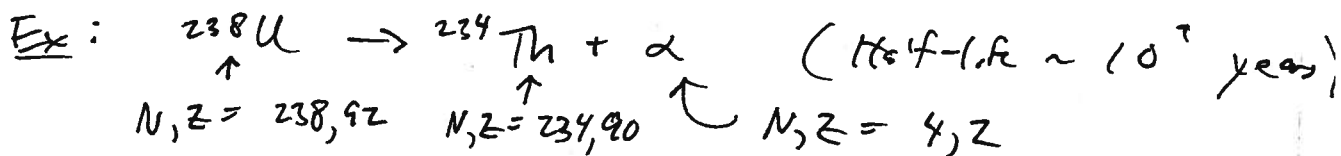
① ψ is continuous

② ψ' is continuous when $V(x)$ is not infinite

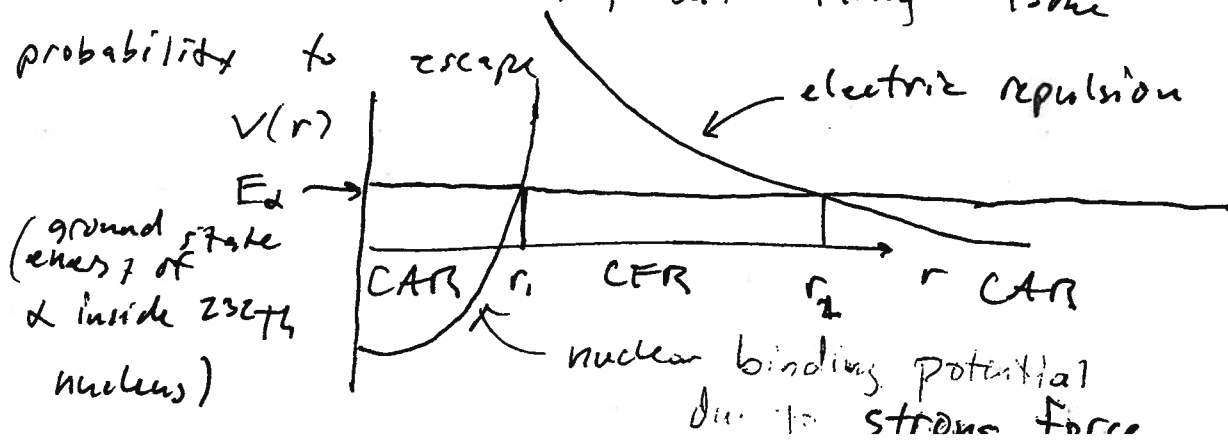
③ ψ should be normalizable. (But we ignore this sometimes when considering "beams of particles")

Alpha Decay

Heavy nuclei like U-238 can decay by emitting an alpha-particle (the nucleus of ${}^4\text{He}$: $\begin{matrix} \text{p} & \text{n} \\ \text{p} & \text{n} \end{matrix}$)

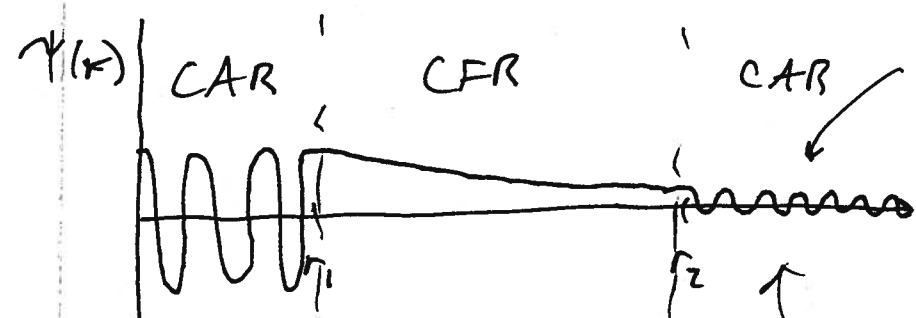


We can think of the alpha particle being bound inside the ${}^{238}\text{Th}$ nucleus, but having some probability to escape



How does the α -particle escape during α -decay?
 Well, an α outside the ^{232}Th nucleus is repelled from the nucleus by the electric force (both are positively charged). So the potential must fall off like $\frac{1}{r}$.

The wavefunction must look like



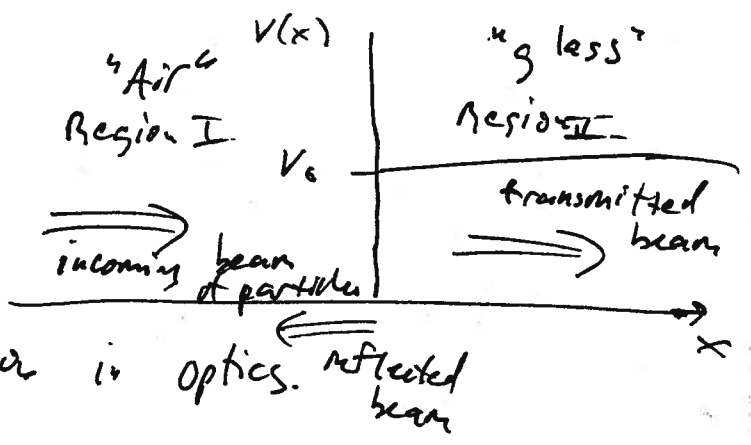
The amplitude of ψ outside r_2 represents the probability of observing α -decay.

The escape of the α -particle is an example of 'QM tunneling' passing through a barrier. The amplitude here is small because of exponential decay in the CFR.

α -decay was the first problem in nuclear physics which was explained by QM.

Potential Step

$$V(x) = \begin{cases} 0 & \text{if } x < 0 \\ V_0 & \text{if } x > 0 \end{cases}$$

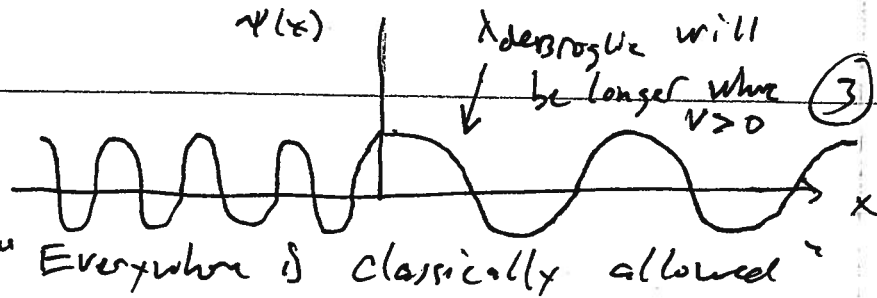


This is the QM equivalent to a change in the index of refraction in optics.

~~Therefore~~

We imagine a beam of particles striking the barrier from the left. How much is transmitted, and how much is reflected?

Two Cases



① $E > V_0$

"Everywhere is classically allowed"

Assume $\psi_{incoming} = A e^{ik_1 x}$ ← incoming momentum eigenstate, our initial condition

Region I: $\psi_1'' = -k_1^2 \psi_1$, $k_1^2 = \frac{2m}{\hbar^2} E$

Region II: $\psi_2'' = -k_2^2 \psi_2$, $k_2^2 = \frac{2m}{\hbar^2} (E - V_0)$

incoming beam

transmitted beam

$\psi_1(x) = A e^{ik_1 x} + B e^{-ik_1 x}$ ← reflected beam, travelling to the left.

$\psi_2(x) = C e^{ik_2 x} + D e^{-ik_2 x}$ ← this represents a beam travelling to the left in Region II.

These wavefunctions are momentum eigenstates, which are un-normalizable. So we

We assume $D = 0$.

Consider A, B, C, D to represent the relative intensities of these beams.

Boundary Conditions

① $\psi_1(x=0) = \psi_2(x=0) \Rightarrow A + B = C$

② $\psi_1'(x=0) = \psi_2'(x=0) \Rightarrow k_1(A - B) = k_2 C$

Solution: $2k_1 A = (k_1 + k_2) C$ (k_1 ② + ①)

$C = \left(\frac{2k_1}{k_1 + k_2} \right) A$

$B = \left(\frac{k_1 - k_2}{k_1 + k_2} \right) A$

relative incoming amplitude

Suppose there is no potential step: $V_0 = \emptyset$.
 Then $k_1 = k_2$ & $B = \emptyset \Rightarrow$ no reflected beam
 $C = 1 \Rightarrow$ 100% transmission.

→ Finish here

Probability Current

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We can define a "probability current" \vec{J} which is analogous to electric current. Where $J > \emptyset$, a particle probability is increasing to the right. Where $J < \emptyset$, particle probability is increasing to the left.

We define in 1D $J \equiv \frac{\hbar}{2mi} (\psi^* \psi' - \psi \psi'^*)$

(See Homework #10 for the motivation).

For the simple step,

$$J_{\text{incoming}} = \frac{\hbar}{2mi} (2ik_1 |A|^2) = \frac{\hbar k_1}{m} |A|^2$$

$$J_{\text{transmitted}} = \frac{\hbar k_2}{m} |C|^2$$

$$J_{\text{reflected}} = -\frac{\hbar k_1}{m} |B|^2$$

Define the Transmission Coefficient & Reflection Coefficient:

$$T \equiv \frac{|J_{\text{transmitted}}|}{|J_{\text{incoming}}|} = \frac{k_2 |C|^2}{k_1 |A|^2} = \frac{4k_1 k_2}{(k_1 + k_2)^2} = \frac{4(k_2/k_1)}{(1 + k_2/k_1)^2}$$

$$R \equiv \frac{|J_{\text{reflected}}|}{|J_{\text{incoming}}|} = \frac{|B|^2}{|A|^2} = \frac{(k_1 - k_2)^2}{(k_1 + k_2)^2} = \frac{(1 - k_2/k_1)^2}{(1 + k_2/k_1)^2}$$

Also note that if $E = V_0$, then $k_2 = \emptyset$, & $T = \emptyset$, $R = 100\%$