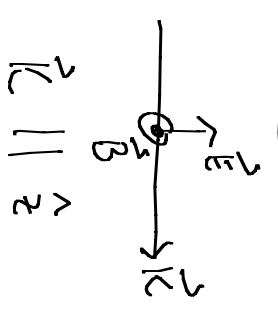
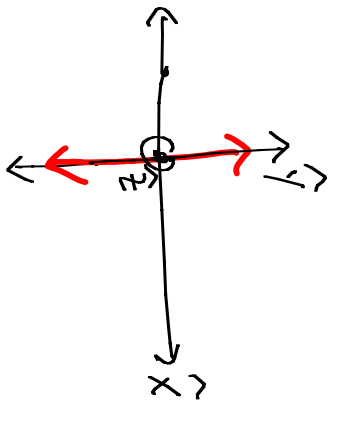


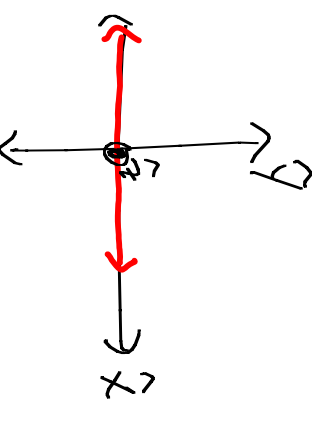
Polarization



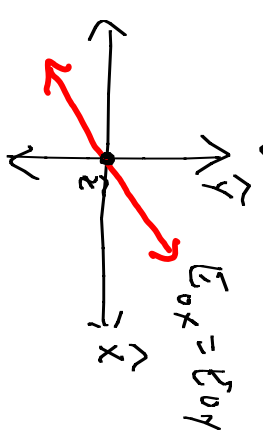
View along $-\vec{k}$



$$\vec{E} = \text{Re} \left\{ E_{0y} \hat{y} e^{-i\omega t} \right\}$$



$$\vec{E} = \text{Re} \left\{ E_{0x} \hat{x} e^{-i\omega t} \right\}$$



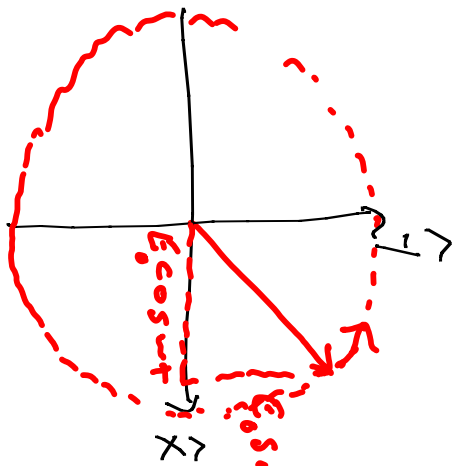
$$\vec{E} = \text{Re} \left\{ (E_{0x} \hat{x} + E_{0y} \hat{y}) e^{-i\omega t} \right\}$$

Superposition w/ Complex Coefs.

$$E_{0x} = A \quad E_{0y} = B e^{i\Delta\phi}$$

$\Delta\phi$: phase difference between E_{0x} and E_{0y}

Example: $E_{0x} = E_0 \quad E_{0y} = E_0 e^{i\Delta\phi}, \quad \Delta\phi = \frac{\pi}{2}$



$$\vec{E} = \text{Re} \left\{ (E_0 \hat{x} + E_0 e^{i\frac{\pi}{2}} \hat{y}) e^{-i\omega t} \right\}$$

$$= \text{Re} \left\{ E_0 (\hat{x} + i\hat{y}) e^{-i\omega t} \right\}$$

$$X: \text{Re} \left\{ E_0 e^{-i\omega t} \right\} = E_0 \frac{e^{i\omega t} + e^{-i\omega t}}{2} = E_0 \cos \omega t$$

$$Y: \text{Re} \left\{ E_0 i e^{-i\omega t} \right\} = E_0 \frac{i e^{-i\omega t} - i e^{i\omega t}}{2}$$

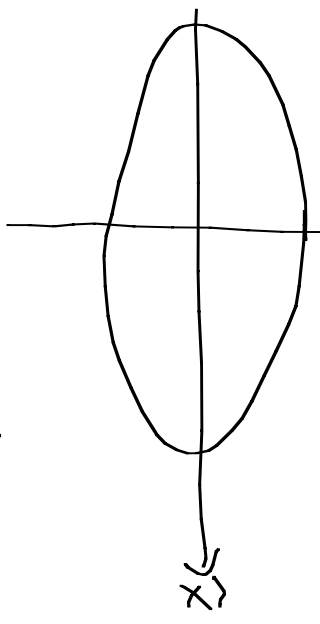
(RCP by $\Delta\phi = -\frac{\pi}{2}$) $= E_0 \frac{e^{i\omega t} - e^{-i\omega t}}{2i} = E_0 \sin \omega t$

$$|\vec{E}| = \sqrt{E_0^2 \cos^2 \omega t + E_0^2 \sin^2 \omega t} = E_0$$

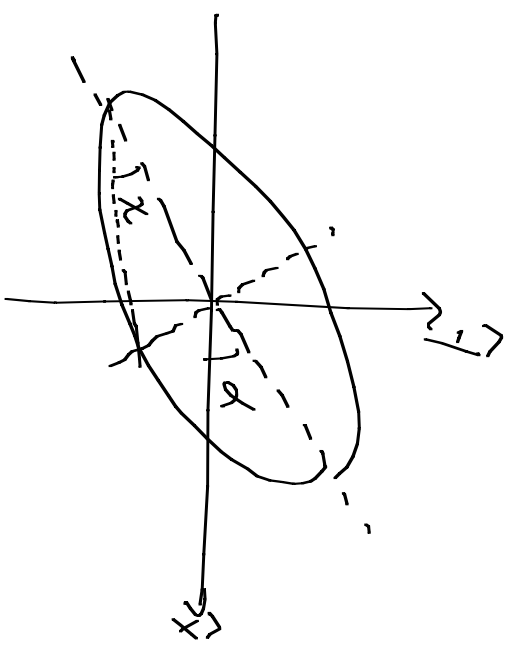
General case:

$|E_{ox}| \neq |E_{oy}|$ $\Delta\phi$ arbitrary

$|\Delta\phi| = \pi/2$



$|\Delta\phi| \neq \pi/2$



α : angle of inclination

χ : ellipticity

$\chi = 0$ linear

$\chi = \pi/4$ circular

Nomenclature: Jones vectors

$$\vec{E} = \text{Re} \{ E_x \hat{x} + E_y \hat{y} \} \longrightarrow \begin{bmatrix} E_x \\ E_y \end{bmatrix}$$

eg. $E_{\theta x} = |E_x|$, $E_{\theta y} = |E_y| \rightarrow$ find α, γ

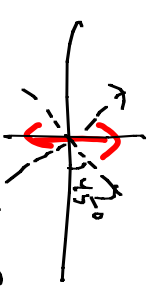
Basis: \hat{x}, \hat{y} basis $\begin{bmatrix} A \\ B \end{bmatrix}$

Rotation matrix

$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

Example: Use $+45^\circ$, -45°

$$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{matrix} \leftarrow \text{vertical} \\ \text{linearly} \\ \text{pol.} \end{matrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$



$$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

Polarization Elements (polarizers, etc)

Matrices:

$$\begin{bmatrix} A \\ B \end{bmatrix} \xrightarrow{\text{Polarizer TA}} \begin{bmatrix} 0 \\ B \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ B \end{bmatrix}$$

$$\begin{bmatrix} A \\ B \end{bmatrix} \xrightarrow{\text{Polarizer TA}} \begin{bmatrix} A \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} A \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} 0 \\ B \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} A \\ 0 \end{bmatrix}$$

Polarizer w/ TA at θ from vertical:

$$\begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$= \begin{bmatrix} \sin^2\theta & \sin\theta\cos\theta \\ \sin\theta\cos\theta & \cos^2\theta \end{bmatrix}$$

Phase Retarder

Birefringence: n is polarization-dependent

$$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\Delta\phi} \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} A \\ B e^{i\Delta\phi} \end{bmatrix}$$

Examples:

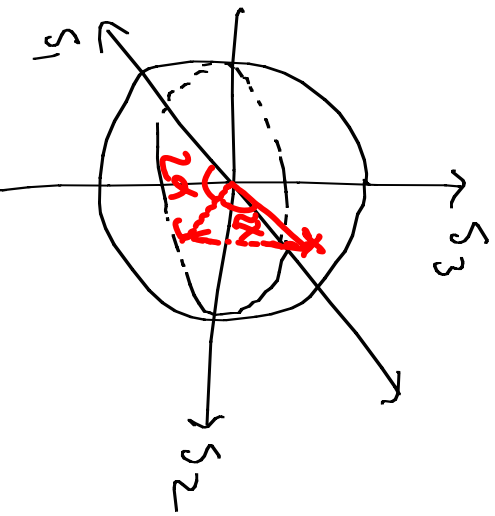
$\Delta\phi = \frac{\pi}{2}$ ("QWP") initial polarization linear @ 45°

$$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\frac{\pi}{2}} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ i \end{bmatrix} \rightarrow \text{circular polarization}$$

$\Delta\phi = \pi$ ("HWP")

$$\begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \rightarrow \text{linearly polarized @ } -45^\circ$$

Alternative nomenclature: Stokes parameters



$$S_0 = I$$

$$S_1 = I \cos 2\alpha \cos 2\chi = E_x^2 - E_y^2$$

$$S_2 = I \sin 2\alpha \cos 2\chi = E_y^2 - E_{-y}^2$$

$$S_3 = I \sin 2\chi = E_{LCP}^2 - E_{RCP}^2$$

Experimentally
measurable

QWP: rotation along polar direction (χ)

HWP: rotations along azimuthal direction (α)