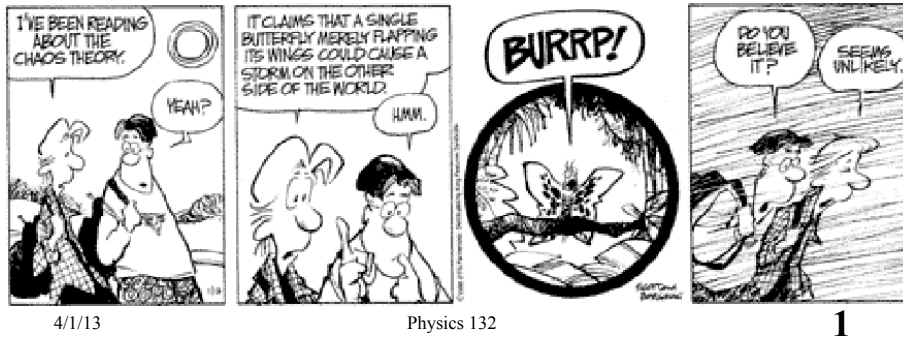


April 1, 2013 Physics 132 Prof. E. F. Redish

■ **Theme Music: Elvis Presley**
All Shook Up
Cartoon: Scott & Borgman
Zits



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1

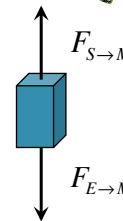
Summary with Equations:
 Mass on a spring



$$a = \frac{1}{m} F^{net}$$

$$F^{net} = -kx$$

Measured from where?



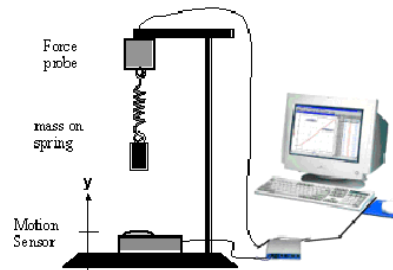
$$a = -\omega_0^2 x$$

$$\omega_0^2 = \frac{k}{m}$$

$$x(t) = A \cos(\omega_0 t + \phi)$$

$$\omega_0 = \frac{2\pi}{T}$$

Interpret!



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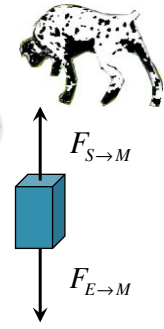
2

Summary with Equations: Mass on a spring (Energy)

Measured from where?

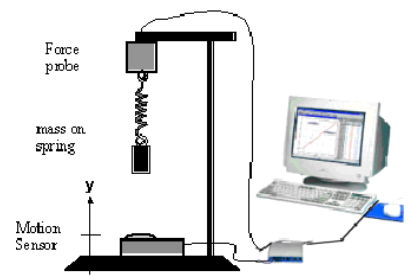
$$E = \frac{1}{2}mv^2 + mgh + \frac{1}{2}k(\Delta l)^2$$

$$E_i = E_f$$



$F_{S \rightarrow M}$ (upward arrow)

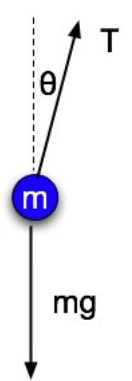
$F_{E \rightarrow M}$ (downward arrow)



Force probe
mass on spring
Motion Sensor

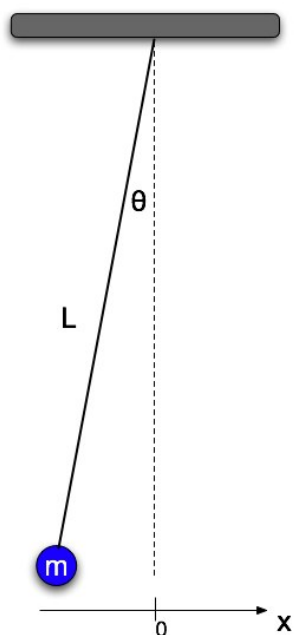
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The Long Pendulum



Force vectors: T (tension), mg (weight)

Angle: θ



Length: L

Angle: θ

Coordinate system: x axis, origin 0

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Pendulum motion energy

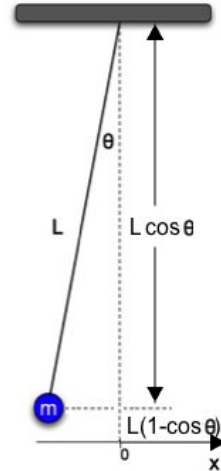
$$E_0 = \frac{1}{2}mv^2 + mgh = \frac{1}{2}mv^2 + mgL(1 - \cos\theta)$$

$$\cos\theta \approx 1 - \frac{1}{2}\theta^2$$

$$E_0 \approx \frac{1}{2}mv^2 + \frac{1}{2}[mgL]\theta^2$$

$$\theta \approx \sin\theta = \frac{x}{L}$$

$$E_0 \approx \frac{1}{2}mv^2 + \frac{1}{2}kx^2 \quad k = \frac{mg}{L}$$



Same as mass on a spring!
 Just with a different $\omega_0^2 = k/m = g/L$

What's the period? Why doesn't it depend on m?

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5

Foothold ideas: Damped oscillator 1



- Amplitude of an oscillator tends to decrease. Simplest model is viscous drag.

$$ma = -kx - bv$$

$$\frac{d^2x}{dt^2} + \gamma \frac{dx}{dt} + \omega_0^2 x = 0 \quad \gamma = \frac{b}{m} \quad \omega_0 = \sqrt{\frac{k}{m}}$$

- Solution:

$$x(t) = A_0 e^{-\gamma t/2} \cos(\omega_1 t + \phi)$$


$$\omega_1 = \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$$

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Foothold ideas: Damped oscillator 2



- Competing time constants:

$$\frac{\gamma}{2} = \frac{1}{\tau}$$

Decay time

$$\frac{\omega_0}{2\pi} = \frac{1}{T}$$


Period

$$Q = \frac{\omega_0}{\gamma} = \pi \frac{\tau}{T}$$

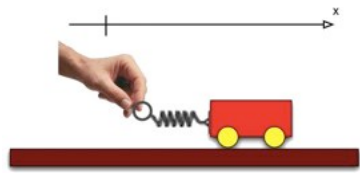
Tells which force dominates: restoring or damping.
- If:
 - $\omega_0 > \gamma/2$ underdamped: oscillates
 - $\omega_0 = \gamma/2$ critically damped: no oscillation, fastest decay
 - $\omega_0 < \gamma/2$ over damped: no oscillation, slower decay

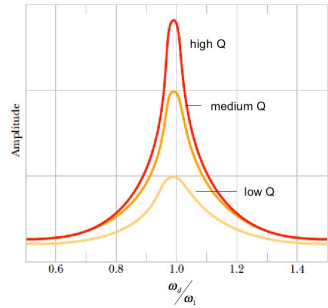
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Foothold ideas: Driven oscillator



- Adding an oscillating force.
- When the extra oscillating force (driver) matches the natural frequency of the oscillator you get a big displacement (**resonance**). Otherwise, not much.





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