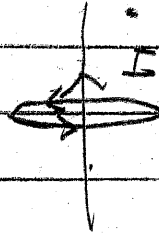


FORMULAE FOR WEEK 9

$$\sum \vec{E} \cdot \Delta \vec{A} = \frac{1}{\epsilon_0} \sum Q$$

$$\sum \vec{B} \cdot \Delta \vec{l} = \mu_0 \sum I_i$$

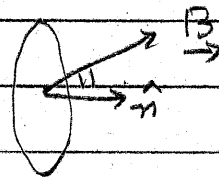
$$\vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$$



$$\sum \vec{E}_{\text{ENC}} \cdot \Delta \vec{l} = - \frac{\Delta \Phi_B}{\Delta t}, \quad \sum \vec{E}_{\text{ENC}} \cdot \Delta \vec{A} = 0$$

$$\vec{F}_B = q [\vec{v} \times \vec{B}]$$

$$\Phi_B = \vec{B} \cdot \Delta \vec{A} = B \Delta A \cos(\hat{n}, \vec{B})$$



$$P_W = I^2 R$$

## Solutions Week 9.

9.1. (i) If you remember Gauss law, we have

$$\sum_C \vec{E} \cdot \Delta \vec{A} = \frac{1}{\epsilon_0} \sum Q_i$$

where the summation is over a closed surface.

In Analogy, if you write the same equation for the magnetic field, you will get

$$\sum_C \vec{B} \cdot \Delta \vec{A} = \mu_0 \sum m_i$$

where,  $m_i$  are the magnetic charges or monopoles.

However, since  $\sum_C \vec{B} \cdot \Delta \vec{A} = 0$

$$\Rightarrow \sum m_i = 0 \text{ always}$$

This simply means there are no independent magnetic charges, and thus the elementary generators of  $\vec{B}$  field are magnetic dipoles.

(ii) Since the  $\vec{B}$  field lines are produced by magnetic dipoles, they always close on themselves, and thus there is no beginning or end.



As regards  $\vec{B}$  fields produced by currents, they also circulate around the currents.

9-2 A Coulomb  $\vec{E}$ -field is produced by a static charge

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r}$$

so it starts at +ive charges and ends at -ive charges.



yielding  $\sum \vec{E} \cdot \Delta \vec{A} = \frac{1}{\epsilon_0} \sum Q_i$  (Gauss's Law)

A non-coulomb  $\vec{E}$  field appears in every loop surrounding a region where the flux of  $\vec{B}$  is varying as a function of time. Hence,  $\vec{E}_{enc}$  lines close on themselves and it is the circulation of  $\vec{E}_{enc}$  around a closed loop that is given by  $\frac{\Delta \Phi_B}{\Delta t}$ .

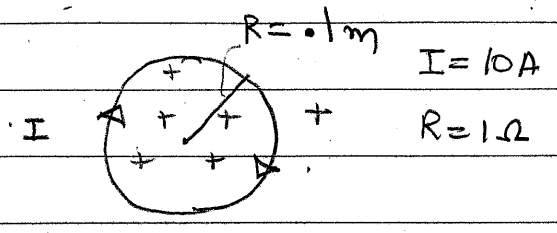
That is,  $\sum_c \vec{E}_{enc} \cdot \Delta \vec{l} = - \frac{\Delta \Phi_B}{\Delta t}$  (Faraday-Lenz)

The minus sign on the right hand side tells us that the sense of  $\vec{E}_{enc}$  must be such as to OPPOSE the change in  $\Phi_B$  that gives rise to the  $\vec{E}_{enc}$ .

9-3

Since the  $\vec{E}_{enc}$  lines close on themselves so the total flux of  $\vec{E}_{enc}$  through any closed surface must be zero!

9.4)  $\mathcal{E} = - \frac{\Delta \Phi}{\Delta t}$



Using Ohm's law,  $\mathcal{E} = \Delta V = IR = 10A \times 1\Omega = 10V$

$\Phi = \int \vec{B} \cdot d\vec{A} = B \cdot \pi R^2 \hat{z}$  }  $\because$  the conducting ring lies on a plane  $d\vec{A} = dA \hat{z}$

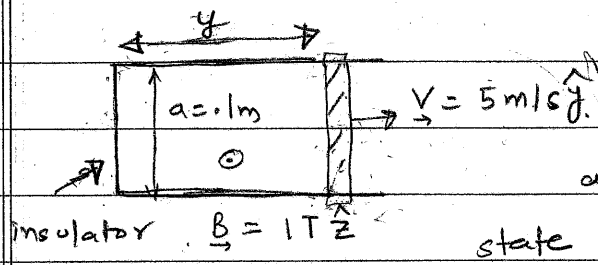
$= -B \pi R^2 \hat{z} \cdot \hat{z}$

$= -B \pi R^2$

$\mathcal{E} = - \frac{\Delta \Phi}{\Delta t} = - \frac{\Delta B}{\Delta t} \pi R^2$  } Area is a constant }

$\Rightarrow 10 = - \frac{\Delta B}{\Delta t} \times \pi \times (0.1)^2 \Rightarrow \frac{\Delta B}{\Delta t} = -318.5 \text{ T/s}$

9.5)



In this case we don't have a closed circuit, so in steady state there won't be any current

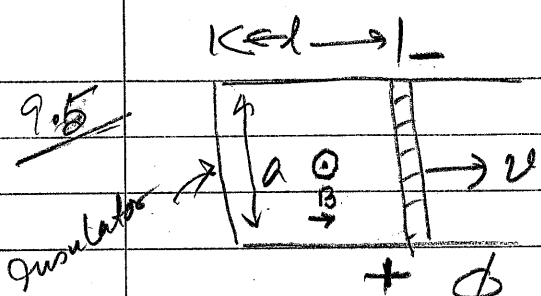
passing through the copper rod.

$\Phi = \int \vec{B} \cdot d\vec{A} = B \cdot A$  } Loop is in a plane  $d\vec{A} = dA \hat{z}$

$= 1 \hat{z} \cdot ay \hat{z} \text{ Tm}^2$  }  $A = ay \hat{z}$

$= ay$

$\mathcal{E} = - \frac{\Delta \Phi}{\Delta t} = - a \frac{\Delta y}{\Delta t} = - a v = -0.1 \times 5 = -0.5 \text{ V}$  the force



$$\vec{B} = 1 \text{ T } \hat{z}$$

$$v = 5 \text{ m/s}$$

$$a = 0.1 \text{ m}$$

$$+ \phi = BA = BA l$$

$$\therefore \frac{\Delta \phi}{\Delta t} = BA \frac{\Delta l}{\Delta t} = BA v$$

$$\mathcal{E} = - \frac{\Delta \phi}{\Delta t} = - BA v$$

$$\therefore \mathcal{E} = - 1 \times 0.1 \times 5 \quad \left[ \begin{array}{l} + \text{ at bottom} \\ - \text{ at top} \end{array} \right]$$

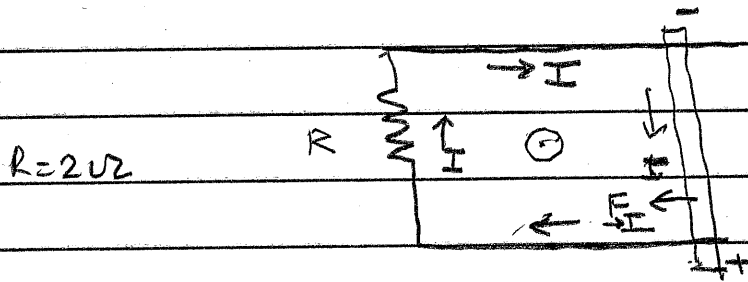
$$= - 0.5 \text{ V}$$

This will produce a "clockwise" \* current, hence the lower end is +ve. Because of the insulator, no actual current flows through the circuit, and hence you do not need to apply a force to move the rod [also see 9.6 for more discussion]

at a constant velocity

\* As the bar moves to the right flux of  $\vec{B}$  out of page is increasing.  $\vec{E}_{nc}$  must counter this by producing a  $\vec{B}$  field into the page. That requires a clockwise "current" [although there is no actual current]. The moving bar plays the role of a battery so current inside it must flow from - to + as indicated on the picture above

9-6 Now there is a current in the bar



so it must experience the force

$$\vec{F} = I[\vec{L} \times \vec{B}] = -I L B \hat{x}$$

Hence to move at constant  $v$ , you must apply a force

$$\begin{aligned} F_{\text{app}} &= +I L B \hat{x} \\ I &= \frac{v L B}{R} \end{aligned} \quad \Rightarrow \quad F_{\text{app}} = + \frac{v L^2 B^2}{R} \hat{x}$$

The current is

$$I = \frac{\mathcal{E}}{R} = \frac{0.5}{2} = 0.25 \text{ A}$$

Incidentally  $F_{\text{app}}$  does  $F_{\text{app}} \cdot v$  amount of work per second

Input Power  $P_{\text{in}} = \frac{v^2 L^2 B^2}{R}$

and this is exactly equal to the power absorbed by the resistor

$$P_{\text{in}} = I^2 R = \frac{v^2 L^2 B^2}{R}$$

9.7.

Initial magnetic flux

$$\phi_i = \pi r^2 B$$

Final flux (after rotation)

$$\phi_f = -\pi r^2 B$$

$$\phi = \vec{B} \cdot \vec{A} = BA \cos(\hat{n}, \vec{B})$$

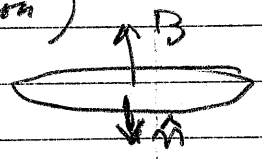
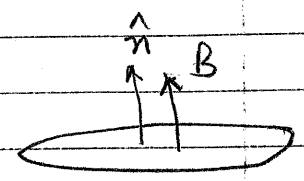
$$\frac{\Delta \phi}{\Delta t} = \frac{\phi_f - \phi_i}{\Delta t} = \frac{-2\pi r^2 B}{\Delta t}$$

But,  $\mathcal{E} = -\frac{\Delta \phi}{\Delta t}$

$$IR = \frac{2\pi r^2 B}{\Delta t}$$

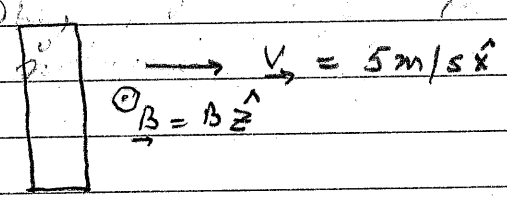
$$\therefore \frac{\Delta Q}{\Delta t} R = \frac{2\pi r^2 B}{\Delta t}$$

$$\therefore \Delta Q = 2\pi r^2 B / R$$



9.8.

This is a case of motional EMF.



Electrons inside rod feel force

$$\vec{F}_B = q[\vec{v} \times \vec{B}] = +e v B \hat{y}$$

They move up creating + charge at bottom = on top.

This generates an  $\vec{E}$  field which causes electrons to feel force  $\vec{F}_E = -e E \hat{y}$

9-8 Contd. Equilibrium will prevail when

$$\vec{F}_E + \vec{F}_B = 0.$$

That is

$$e v B - e E = 0$$

$$E = v B.$$

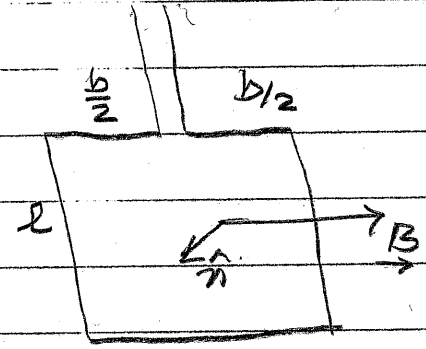
which sets up an EMF

$$E = v B l$$

exactly as in problem 9-5.

9-9

In order to make a generator we must rotate the coil at angular velocity  $\omega$  about



the  $y$ -axis. If so, the flux of  $B$  through the coil will vary with time and an  $E_{nc}$  will appear in the coil generating

$$\text{the emf} = \sum \vec{E}_{nc} \cdot \underline{A}$$

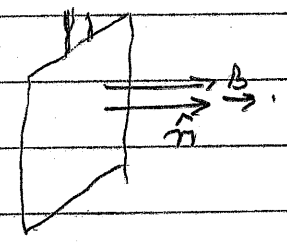
Let us begin at  $t=0$

with  $\hat{n} \parallel \vec{B}$ . As coil

rotates the angle between

$\hat{n}$  and  $\vec{B}$  will vary as

$$\theta = \omega t$$



$$[\theta = \theta_0 + \omega t, \theta_0 = 0]$$

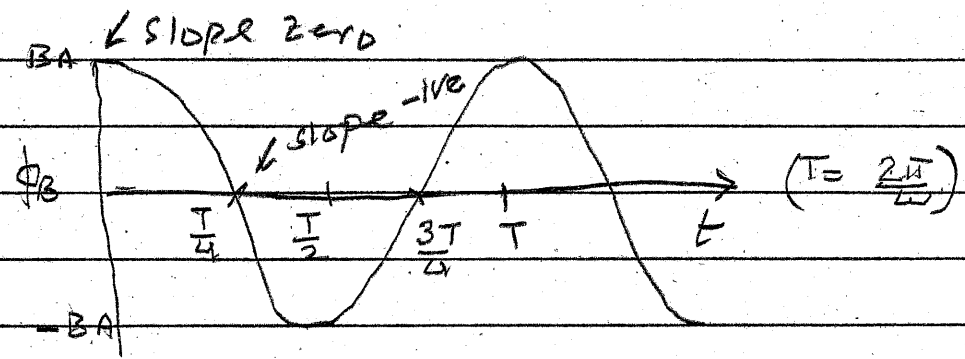
The flux of  $\vec{B}$  is

$$\phi_B = \vec{B} \cdot \underline{A} = B A \cos(\hat{n}, \vec{B})$$

$$= B A \cos \omega t.$$

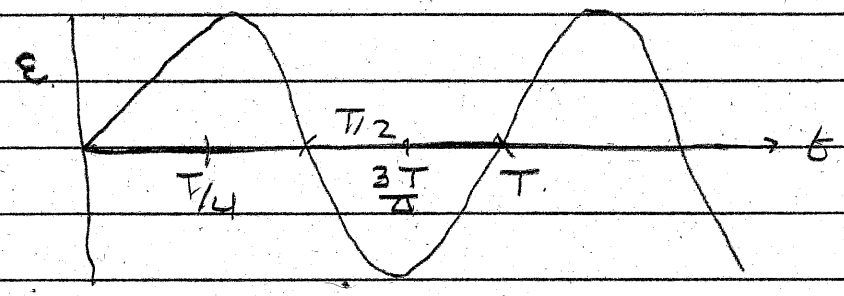
Plot  $\phi_B$  as a function of  $t$  we get





Now 
$$E = \sum_c \vec{E}_c \cdot \Delta \vec{c} = - \frac{\Delta \Phi_B}{\Delta t}$$

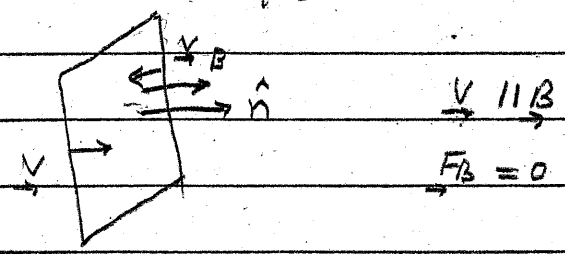
That is the -ive slope of the  $\Phi_B$  vs time curve.



Q-10 From the two diagrams of Prob 9-9 you can see that  $E$  is zero when  $\Phi_B$  is maximum and maximum when  $\Phi_B$  is zero.

One can get a better answer by recalling the result of Prob 9-8.

At the instant when  $\Phi_B$  is maximum  $\hat{n} \parallel \vec{B}$

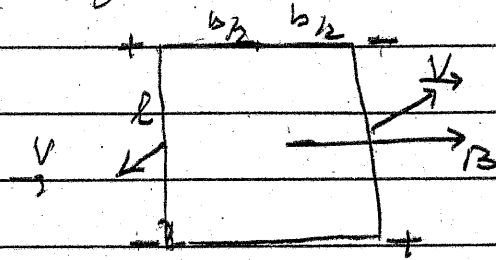


The velocities of the vertical arms are parallel to  $\vec{B}$  so NO MOTIONAL EMF

When  $\cos \theta$  flux is zero

$$V = R \omega I$$

$$V = \pm \frac{b}{2} \omega \hat{z}$$



$V \perp B$ ,  $|\mathbf{V} \times \mathbf{B}|$  is maximum

$$\text{EMF's maximum } 2VBl = 2 \frac{b}{2} \omega Bl = \omega BA$$

$A =$  area of coil.

At other positions  $V$  makes an angle  $\theta$  with  $B$  so emf

$$\text{becomes } = \omega BA \sin \theta = \omega BA \sin \omega t$$

as shown by the second graph in Prob. 9-9.

9-11 The definition of inductance is

$$L = - \frac{\mathcal{E}}{\frac{\Delta I}{\Delta t}}$$

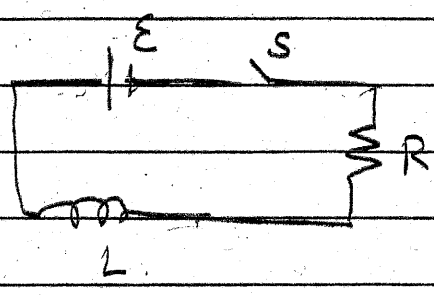
$$\mathcal{E} \text{ is } V, \frac{\Delta I}{\Delta t} \text{ is } \frac{I}{T} \text{ so } \frac{VT}{I}$$

$$R = \frac{V}{I}$$

$$\frac{L}{R} = \frac{\frac{VT}{I}}{\frac{V}{I}} \rightarrow T$$

9-12 In an L-R

circuit when  
switch is  
closed the



battery wants to establish a current through R. L opposes this.

L controls the rate of change of current, so the larger L is, the longer it will take for current to be established.

$$L = - \frac{E}{\frac{di}{dt}}$$

R controls the eventual current ( $\frac{E}{R}$ ), so larger R is, the smaller the current required to complete the process and the quicker it will happen. That is why the characteristic time is  $\frac{L}{R}$ .

$$I_{max} = \frac{E}{R}$$

9-13 Once the inductor has a current in it, there is a B-field in it and the work done by the battery is stored in the B-field. [see next problem] [compare with the case of the capacitor, where the work went into the E-field (problem 6-2)]

9.14

We have  $U_B = \frac{1}{2} LI^2$  //

For a solenoid of  $n$  turns per unit length  
and total length  $l$ ,

Self inductance  $L = \mu_0 n^2 Al$ And,  $B = \mu_0 n I$ then,  $U_B = \frac{1}{2} LI^2$ 

$$= \frac{1}{2} \mu_0 n^2 Al \cdot I^2$$

$$= \frac{1}{2\mu_0} (\mu_0 n I)^2 \cdot Al$$

$$= \frac{1}{2\mu_0} B^2 \cdot V \quad (\text{volume } V = Al)$$

$\therefore$  Energy stored per unit volume in

$$\frac{B}{\mu_0} \text{ is } \eta_B = \frac{B^2}{2\mu_0}$$

9.15 (i) time constant  $\tau = L/R$ 

$$\therefore \tau = \frac{10^{-3}}{10} = 10^{-4} \text{ s.}$$

$$(ii) \quad I = I_0 (1 - e^{-t/\tau})$$

$$\text{But, } I = 0.9 I_0$$

$$\therefore 0.9 = 1 - e^{-t/\tau}$$

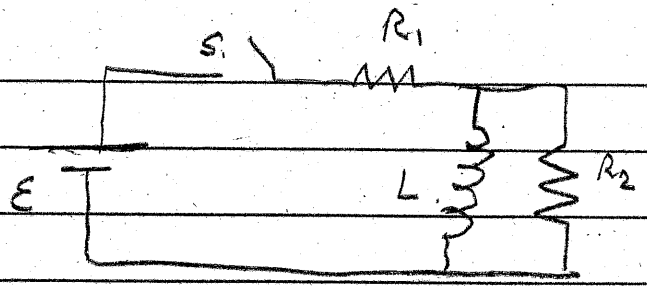
$$\text{or, } e^{-t/\tau} = 0.1$$

$$\therefore -t/\tau = -2.3$$

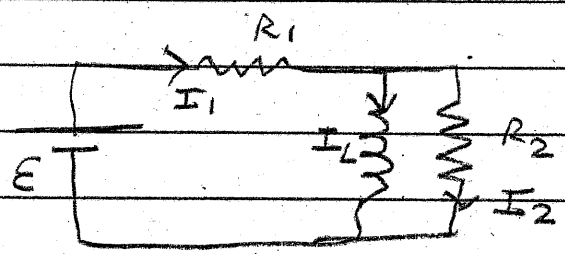
$$\therefore t = 2.3 \tau$$

$$= 2.3 \times 10^{-4} \text{ s. (Ans)}$$

9-16



When you close switch current begins to flow

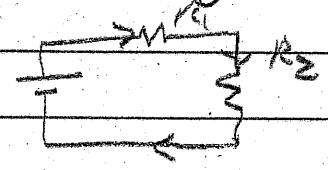


and the junction rule is

$$I_L + I_2 = I_1 \rightarrow \textcircled{1}$$

at  $t = 0^+$  there is no current in the inductor, the battery has just begun to do its thing so  $I_L = 0$

$$I_1 = I_2 = \frac{\mathcal{E}}{R_1 + R_2}$$



A long time later current through L is constant so there is NO potential drop across L,  $R_2$  is parallel to L so  $V_{R_2} = 0, I_2 = 0$

$$I_1 = I_L = \frac{\mathcal{E}}{R_1}$$

$$V_L = 0$$

$$V_{R_2} = 0$$