



Physic² 121: Phundament[°]Is of Phy²ics I

November 20, 2006



D. Roberts

University of Maryland

PHYS 121

Make-Up Exam

- 8:00-9:00
 - Room PHYS 1201
- 12:00-1:00
 - Room PHYS 4220
- 5:00-6:00
 - Room PHYS 1201
- 1201 is a fairly large room (seats ~70)



Chapter 8

Rotational Equilibrium and Rotational Dynamics



D. Roberts

University of Maryland

PHYS 121

Torque and Angular Acceleration

- When a rigid object is subject to a net torque ($\neq 0$), it undergoes an angular acceleration
- The angular acceleration is directly proportional to the net torque
 - The relationship is analogous to $\Sigma F = ma$
 - Newton's Second Law

Moment of Inertia

- The angular acceleration is inversely proportional to the analogy of the mass in a rotating system
- This mass analog is called the *moment of inertia*, I , of the object

$$I \equiv \sum mr^2$$

– SI units are kg m^2

Newton's Second Law for a Rotating Object

$$\Sigma \tau = I \alpha$$

- The angular acceleration is directly proportional to the net torque
- The angular acceleration is inversely proportional to the moment of inertia of the object

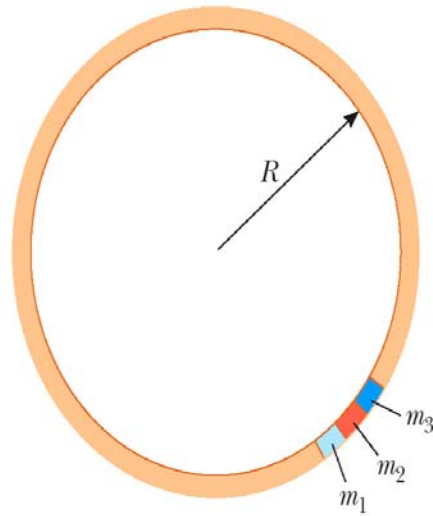
More About Moment of Inertia

- There is a major difference between moment of inertia and mass: the moment of inertia depends on the quantity of matter *and its distribution* in the rigid object.
- The moment of inertia also depends upon the location of the axis of rotation

Moment of Inertia of a Uniform Ring

- Imagine the hoop is divided into a number of small segments, $m_1 \dots$
- These segments are equidistant from the axis

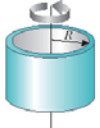
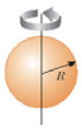
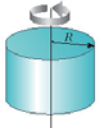



$$I = \sum m_i r_i^2 = MR^2$$



© 2008 Brooks/Cole - Thomson

Other Moments of Inertia

TABLE 8.1
Moments of Inertia for Various Rigid Objects
of Uniform Composition

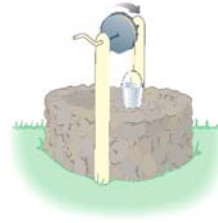
Hoop or thin cylindrical shell $I = MR^2$		Solid sphere $I = \frac{2}{5} MR^2$	
Solid cylinder or disk $I = \frac{1}{2} MR^2$		Thin spherical shell $I = \frac{2}{3} MR^2$	
Long thin rod with rotation axis through center $I = \frac{1}{12} ML^2$		Long thin rod with rotation axis through end $I = \frac{1}{3} ML^2$	

© 2008 Brooks/Cole - Thomson

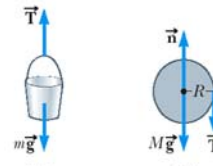
Example, Newton's Second Law for Rotation

- Draw free body diagrams of each object
- Only the cylinder is rotating, so apply $\Sigma\tau = I\alpha$
- The bucket is falling, but not rotating, so apply $\Sigma F = ma$
- Remember that $a = \alpha r$ and solve the resulting equations

- Problem: A solid, frictionless cylindrical reel of mass $M = 3\text{ kg}$ and radius $R = 0.4\text{ m}$ is used to draw water from a well. A bucket of mass 2 kg is attached to a cord wrapped around the cylinder.
 - Find the tension in the cord and acceleration of the bucket



(a)



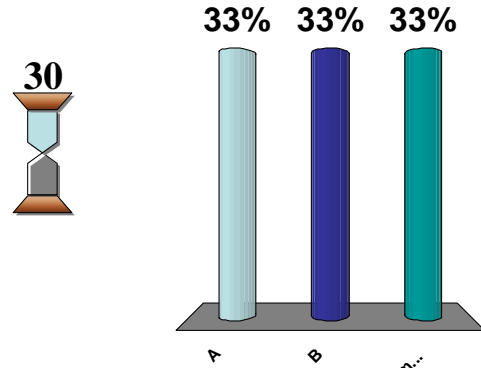
© 2006 Brooks/Cole - Thomson



Two cylinders of the same size and mass roll down an incline. Cylinder A has most of its weight concentrated at the rim, while cylinder B has most its weight concentrated at the center. Which reaches the bottom of the incline first?



1. A
2. B
3. Both reach at the same time



0 of 5

1	2	3	4	5															
---	---	---	---	---	--	--	--	--	--	--	--	--	--	--	--	--	--	--	--

Rotational Kinetic Energy

- An object rotating about some axis with an angular speed, ω , has rotational kinetic energy $\frac{1}{2}I\omega^2$
- Energy concepts can be useful for simplifying the analysis of rotational motion

Total Energy of a System

- Conservation of Mechanical Energy

$$(KE_t + KE_r + PE_g)_i = (KE_t + KE_r + PE_g)_f$$

- Remember, this is for conservative forces, no dissipative forces such as friction can be present
- Potential energies of any other conservative forces could be added

Work-Energy in a Rotating System

- In the case where there are dissipative forces such as friction, use the generalized Work-Energy Theorem instead of Conservation of Energy
- $W_{nc} = \Delta KE_t + \Delta KE_R + \Delta PE$