

Newton 2 is a vector equation

- We have sort of been assuming that up and down forces were independent of sideways forces.
- This tests out true in detail. It means N2 is a vector equation: \vec{F}^{net}

 $\vec{a} = \vec{F}^{net} / m$

■ A vector equation is a way of writing 2 equations at once:

 $a_x = F_x^{net} / m \qquad a_y = F_y^{net} / m$

Our velocity and acceleration definitions generalize easily

$$\begin{split} \left\langle \vec{v} \right\rangle &= \frac{\Delta \vec{r}}{\Delta t} & \Delta \vec{r} = \vec{r}_f - \vec{r}_i \\ \left\langle \vec{a} \right\rangle &= \frac{\Delta \vec{v}}{\Delta t} & \Delta \vec{v} = \vec{v}_f - \vec{v}_i \end{split}$$

$$\Delta v = v_f - v$$

$$\Delta v = v_f - v$$

$$\langle v_x \rangle = \frac{\Delta v_x}{\Delta t}$$
 $\langle v_y \rangle = \frac{\Delta v_x}{\Delta t}$ $\langle a_y \rangle = \frac{\Delta v_x}{\Delta t}$ $\langle a_y \rangle = \frac{\Delta v_x}{\Delta t}$

If a is constant

Recap: Coordinates and Vectors

- Set up a coordinate system
 - Pick an origin
 - Pick 3 perpendicular directions
 - Choose a measurement scale
- Each point in space in then specified by three numbers: the x, y, and z coordinates.
- The position vector for a particular position is an arrow drawn from the origin to that position.

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Recap: Motion in a plane (2-dimensional coordinates)

- We now have 2 directions to specify. We must
 - Choose a reference point (origin)
 - Pick 2 perpendicular axes (x and y)
- We specify our x and y directions by drawing little arrows of unit length in their positive direction.

i, j

 \blacksquare A position specified by a point (x,y) is written

$$\vec{r} = x\hat{i} + y\hat{j}$$

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Adding Vectors: Meaning

- A position vector, r

 , represents a displacement from the origin.
- We define the sum of two vectors as the results of their successive displacements.



$$\vec{r} = \vec{r_1} + \vec{r_2}$$

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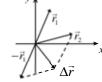
Subtracting Vectors: Meaning

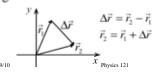
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■ We define the difference of two vectors from the definition of sum.

$$\Delta \vec{r} = \vec{r}_2 - \vec{r}_1 = \vec{r}_2 + (-\vec{r}_1)$$

Or: The difference is what has to be added to the first to give the second.





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Adding Vectors: Methods There are 3 mathematical ways to add vectors Geometry! $\vec{r}_i = x_i \hat{i} + y_i \hat{j}$ $\vec{r}_2 = x_2 \hat{i} + y_2 \hat{j}$ $\vec{r}_1 + \vec{r}_2 = x_1 \hat{i} + y_1 \hat{j} + x_2 \hat{i} + y_2 \hat{j}$ $= x_1 \hat{i} + x_2 \hat{i} + y_1 \hat{j} + y_2 \hat{j}$ $= x_1 \hat{i} + x_2 \hat{i} + y_1 \hat{j} + y_2 \hat{j}$ $= (x_1 + x_2) \hat{i} + (y_1 + y_2) \hat{j}$ head parallelogram to tail rule $y_{129/10} = y_{129/10} = y_{129/10}$

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