

Kinematics – Description of Motion in One Dimension [Along x-axis]. (Point Particles)

Definitions

Position Vector:

$$\underline{x}(t) = A\hat{x} \quad \text{or} \quad -A\hat{x}$$

A is magnitude

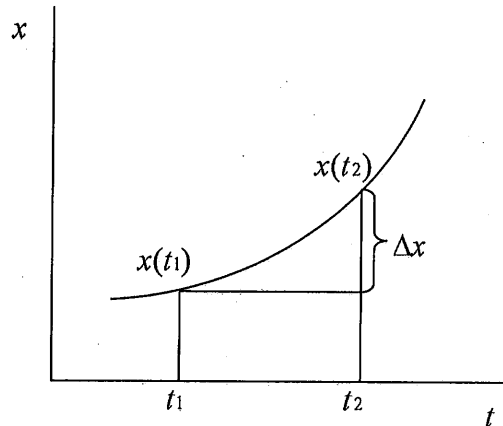
$+\hat{x}$ vector points right

$-\hat{x}$ vector points left

Displacement Vector: Measures change of position

$$\Delta \underline{x} = \underline{x}(t_2) - \underline{x}(t_1)$$

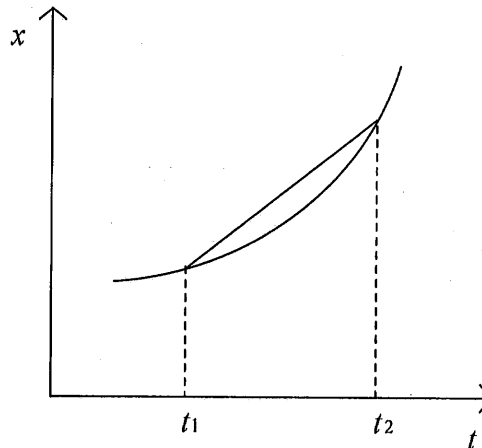
Here, $\Delta \underline{x}$ is along $+\hat{x}$



Average Velocity Vector: Measures rate of change of position with time over a finite time interval ($t_2 - t_1$)

$$\langle \underline{v} \rangle = \frac{x(t_2) - x(t_1)}{(t_2 - t_1)} \hat{x}$$

It is the slope of the chord



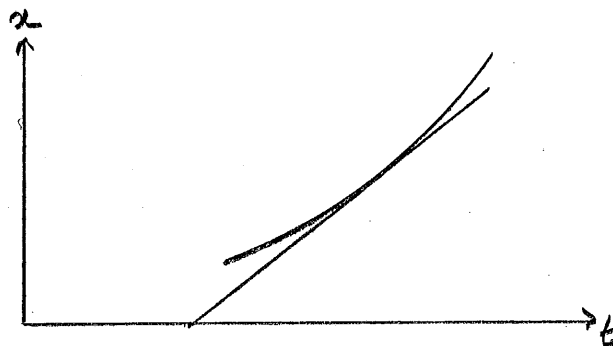
Instantaneous Velocity Vector: Measures rate of change of position with time when time interval goes to zero

$$\Delta t \rightarrow 0$$

$$\Delta x \rightarrow 0$$

$$\underline{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \underline{x}}{\Delta t}$$

Slope of tangent to x vs. t graph



Average Acceleration Vector: Measures rate of change of velocity vector during a finite time interval.

$$\langle \underline{a} \rangle = \frac{\underline{v}(t_2) - \underline{v}(t_1)}{(t_2 - t_1)}$$

Slope of chord in v vs. t graph

Instantaneous Acceleration Vector: Measures rate of change of velocity vector when time interval goes to zero

$$\Delta t \rightarrow 0$$

$$\Delta v \rightarrow 0$$

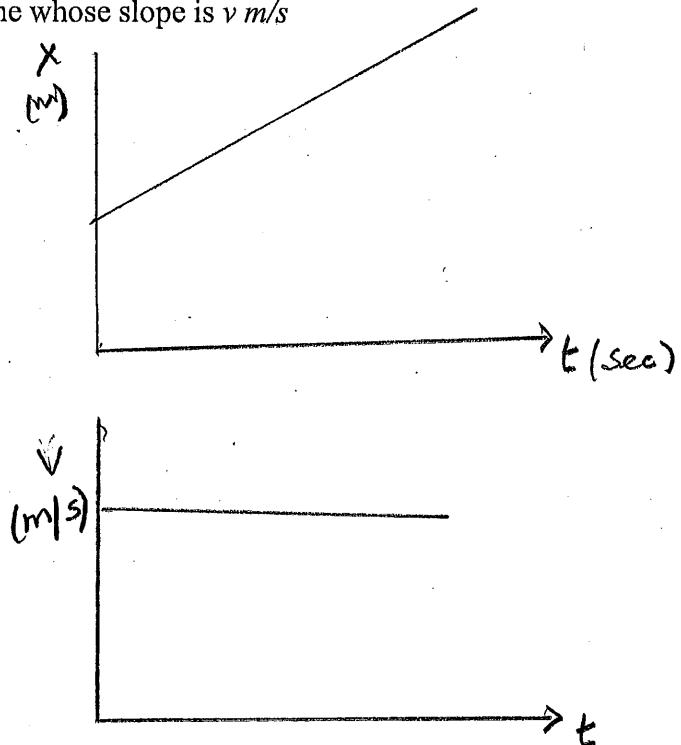
$$\underline{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t}$$

UNIFORM MOTION

$$\underline{a} = 0$$

$$\underline{v} = v\hat{x} \text{ is constant}$$

In this case x vs. t graphs will be straight line whose slope is v m/s

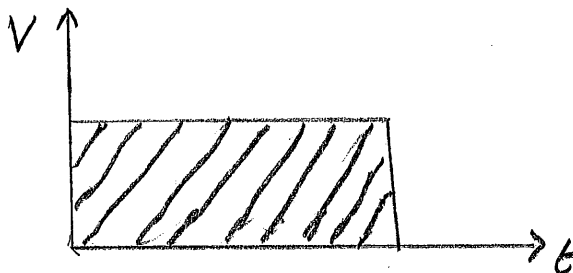


Since v measures change in x every second, a table of Δx vs. t will look like

t (sec)	Δx (m)
0	0
1	v
2	$2v$
3	$3v$
4	$4v$

That is Δx is equal to area under v vs. t graph. In t seconds

$$\Delta x = vt$$



To write down x at t seconds, we must know where object was at $t = 0$ and get uniform motion equation

$$\underline{x}(t) = \underline{x}(0) + \underline{v}t = (x_i + vt)\hat{x} \quad \longrightarrow (1)$$

x_i = initial position

So the rule is: To calculate $\underline{x}(t)$ add the area under \underline{v} vs. t graphs to the value of \underline{x} at $t = 0$.

Next: MOTION WITH CONSTANT ACCELERATION

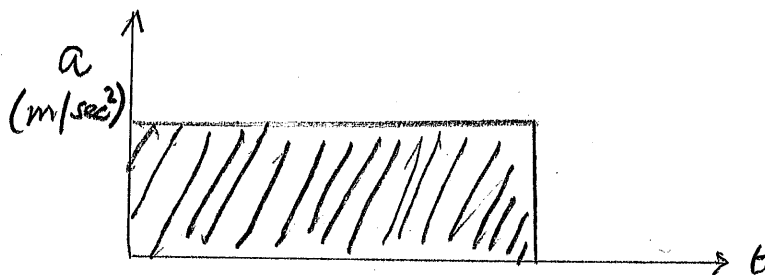
$$\underline{a} = a\hat{x} \quad (2)$$

Now \underline{v} is NOT CONSTANT. Indeed, since a measure change of \underline{v} every second \underline{v} vs. t graphs must look like

Now \underline{v} is changing by a m/s every second so table of Δv vs. t must be

t (sec)	Δv (m/s)
0	0
1	a
2	$2a$
3	$3a$
4	$4a$

Change of v during t seconds is area under a vs. t graph.

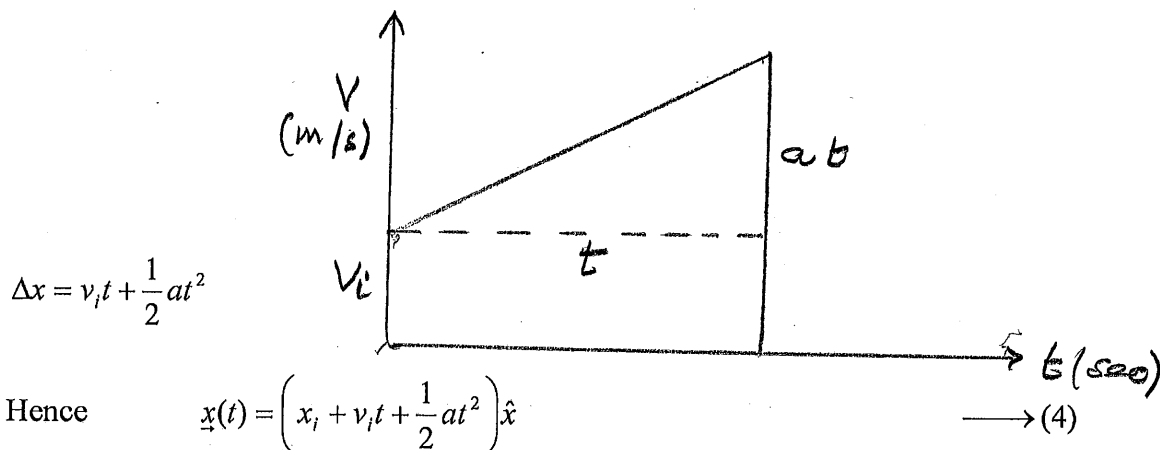


And again to write \underline{v} at any time t we must know \underline{v} at $t = 0$ and write for constant acceleration

$$\underline{v}(t) = (v_i + at)\hat{x} \quad \longrightarrow (3)$$

v_i \hat{x} is initial velocity

- I To calculate x as a function of t we can proceed in two ways:
Use the rule written under Eq(1). Draw graph of Eq(3) then change of x is area under v vs. t graph



$$\Delta x = v_i t + \frac{1}{2} at^2$$

Hence
$$\underline{x}(t) = \left(x_i + v_i t + \frac{1}{2} at^2 \right) \hat{x} \quad \longrightarrow (4)$$

- II We can use (3) to calculate average velocity between 0 and t since v is increasing linearly with time

$$\langle v \rangle = \frac{v_i + v_i + at}{2} = v_i + \frac{at}{2}$$

Displacement $\Delta x = \left(v_i + \frac{at}{2} \right) t$

and again yield Eq(4)

To Summarize the kinematic equations are

$$\underline{a} = a\hat{x} \quad (2)$$

$$\underline{v}(t) = (v_i + at)\hat{x} \quad (3)$$

$$\underline{x}(t) = \left(x_i + v_i t + \frac{1}{2} at^2 \right) \hat{x} \quad (4)$$

Eqs(3) and (4) can be combined to yield a useful relation between magnitudes of v and x

From (3) $t = \frac{v - v_i}{a}$

Substitute in (4)

$$\begin{aligned} x &= x_i + v_i \left(\frac{v - v_i}{a} \right) + \frac{1}{2} a \left(\frac{v - v_i}{a} \right)^2 \\ &= x_0 + \frac{v^2 - v_i^2}{2a} \end{aligned}$$

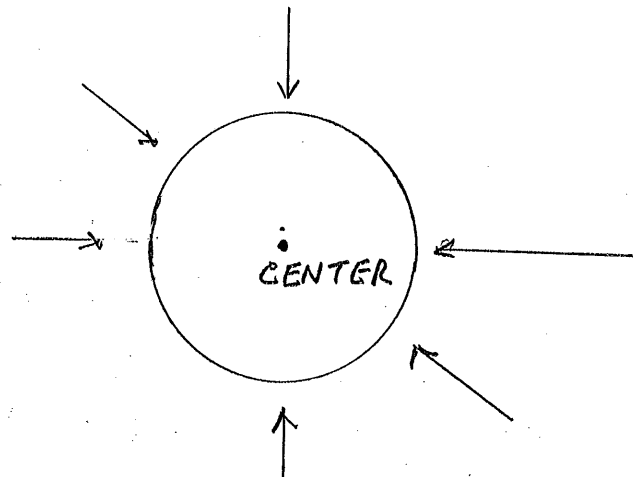
Or

$$v^2 = v_i^2 + 2a(x - x_i) \quad \longrightarrow (5)$$

Eq(5) is useful when you know position and not time.

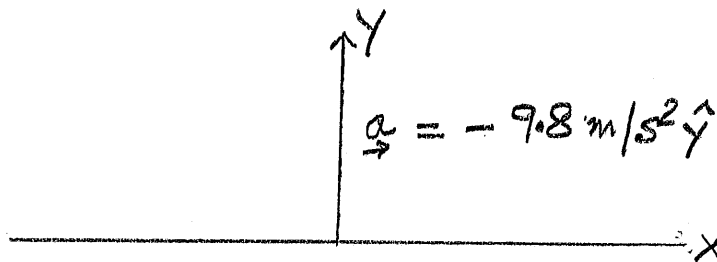
FREE FALL

So, why are we so interested in discussing motion where a is a constant? The reason is that near the surface of the Earth every unsupported object has a constant acceleration of about 9.8 m/s^2 directed along the radius of the Earth and pointing toward the center. — acceleration due to gravity



Locally, we pretend that the Earth is flat, choose coordinate system where x is along horizontal y along vertical with positive up and therefore write that the acceleration due to gravity is

$$\underline{a} = -9.8 \text{ m/s}^2 \hat{y} \quad \text{-(6)}$$



Now we can use Eqs(3),(4), and (5) for motion along y and write

$$y = (v_i - 9.8t) \hat{y} \quad \text{-(7)}$$

$$y = (y_i + v_i t - 4.9t^2) \hat{y} \quad \text{(8)}$$

$$v^2 = v_i^2 - 19.6(y - y_i) \quad \text{-(9)}$$

Notes

- 1 It is very important to note that if you throw a ball straight up or straight down the only quantity you can control is its initial velocity v_i . Once it leaves your hand the motion is controlled only by the Earth via Eqs(6) through (9). **THE ACCELERATION IS THE SAME AT ALL TIMES DURING THE FLIGHT OF THE BALL.**
- 2 Eqs(6) through (9) apply for free fall on the moon or any other planet. The only difference is that the magnitude of \underline{a} is not the same as it is on Earth. For instance, on the moon

$$\underline{a} = -1.63 \text{ m/s}^2 \hat{y} \quad \text{(Moon)}$$

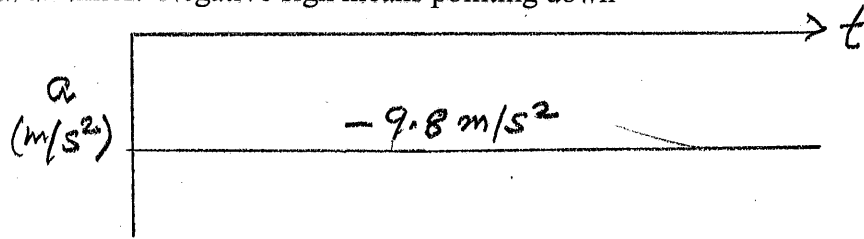
EXAMPLE

Let $\underline{v} = +v_i \hat{y}$ $y_i = 0$. That is, at $t = 0$ an object is thrown straight up with a velocity of $+v_0 \text{ m/s}^2 \hat{y}$ starting from the ground ($y_i = 0$). It will go up to some height. Turn around and come back to ground according to Eqs(5) through (9). We can plot its acceleration, velocity and position as a function of time.



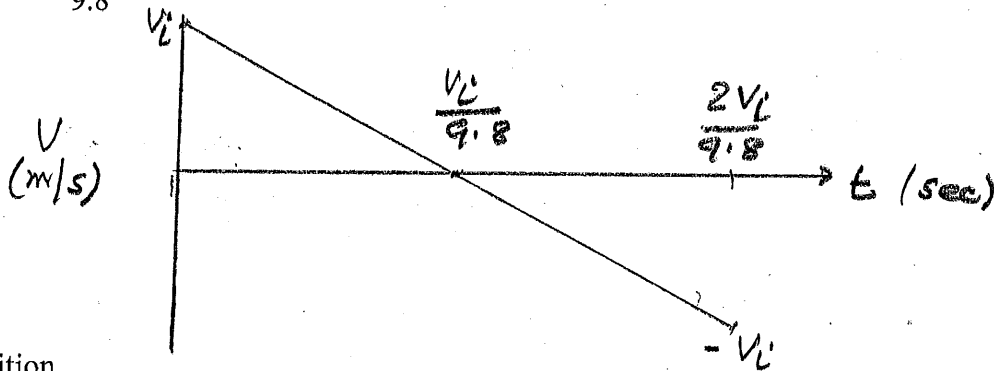
Acceleration

Constant at all times. Negative sign means pointing down

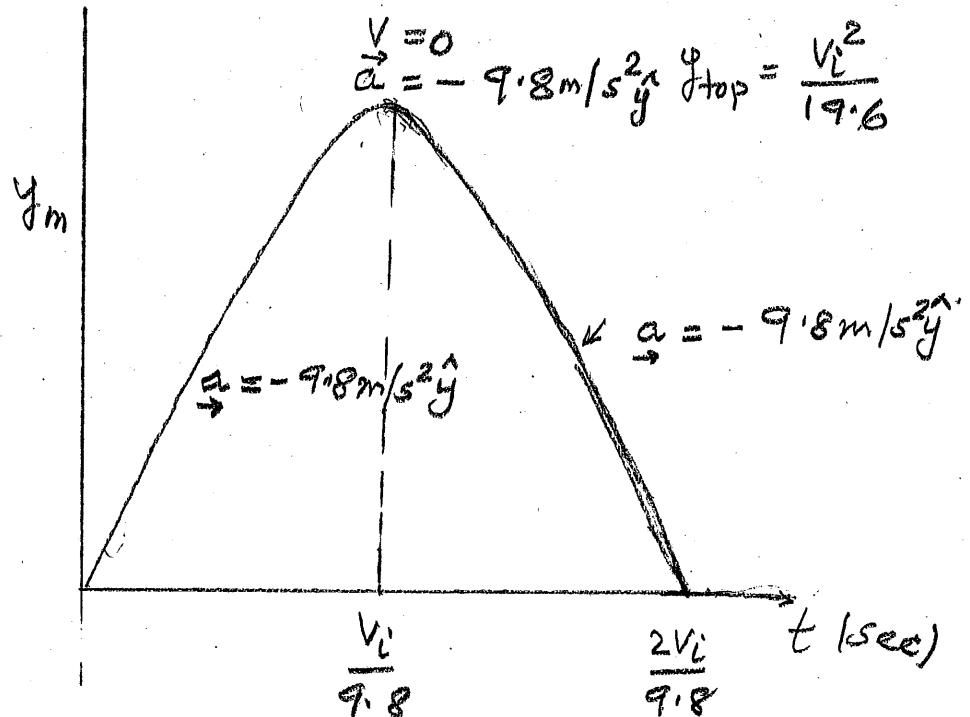
Velocity

Reaches highest point in $\frac{v_i}{9.8}$ seconds. At that point, velocity is zero so it stops rising. Returns to

Earth in $\frac{2v_i}{9.8}$ seconds and has velocity $-v_0 \hat{y}$ just before it hits the ground.

Position

At highest point, $v = 0$ so from Eq(9) $y_{top} = \frac{v_i^2}{19.6}$.

Combines Flight Picture